

# IQI 04, Seminar 4

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Produced with pdflatex and xfig

- One qubit rotations.
- Universality for one qubit.

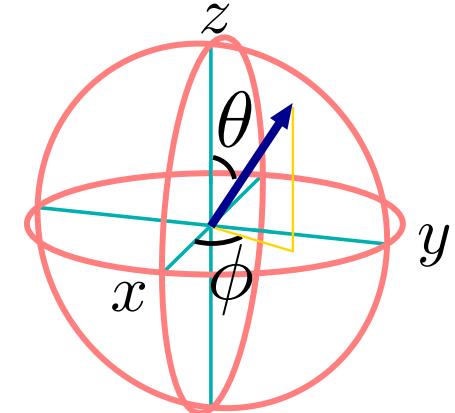
E. “Manny” Knill: [knill@boulder.nist.gov](mailto:knill@boulder.nist.gov)

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# Rotations I

- Rotation gates rotate the state in the Bloch sphere representation.

$$\begin{aligned}\alpha|0\rangle + \beta|1\rangle &\cong \\ e^{-i\phi/2} \cos(\theta/2)|0\rangle \\ + e^{i\phi/2} \sin(\theta/2)|1\rangle\end{aligned}$$



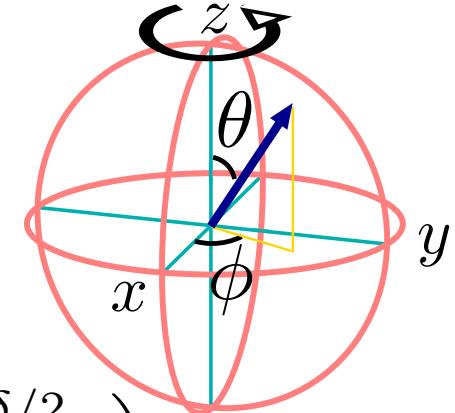
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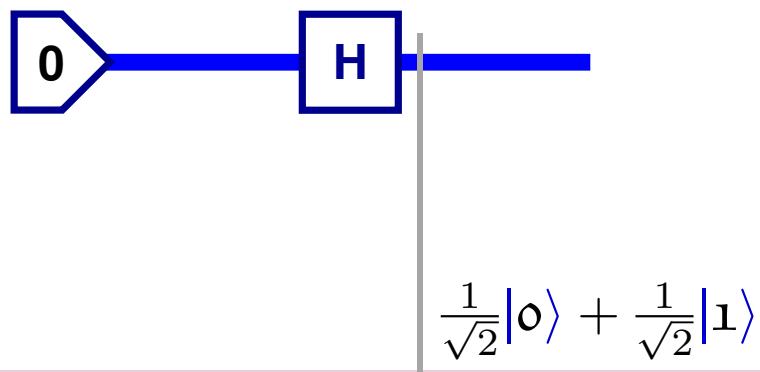
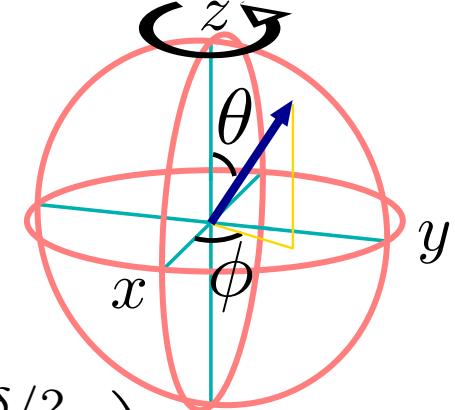
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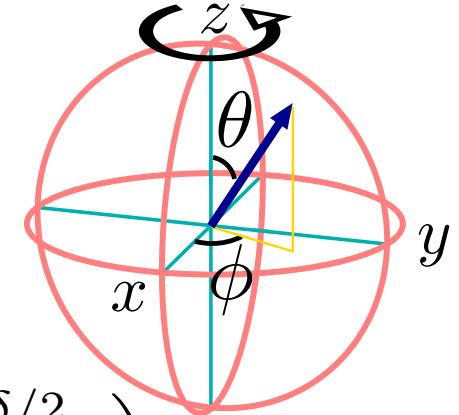
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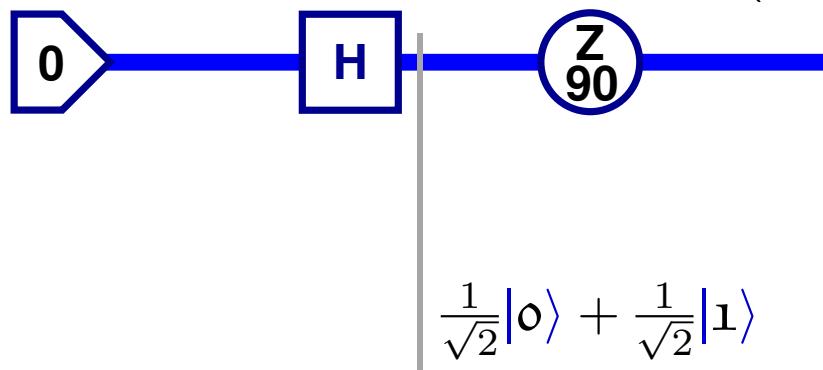


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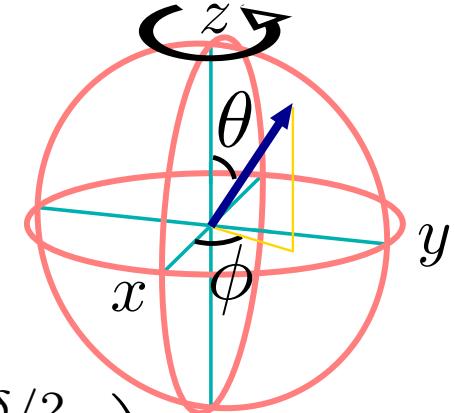
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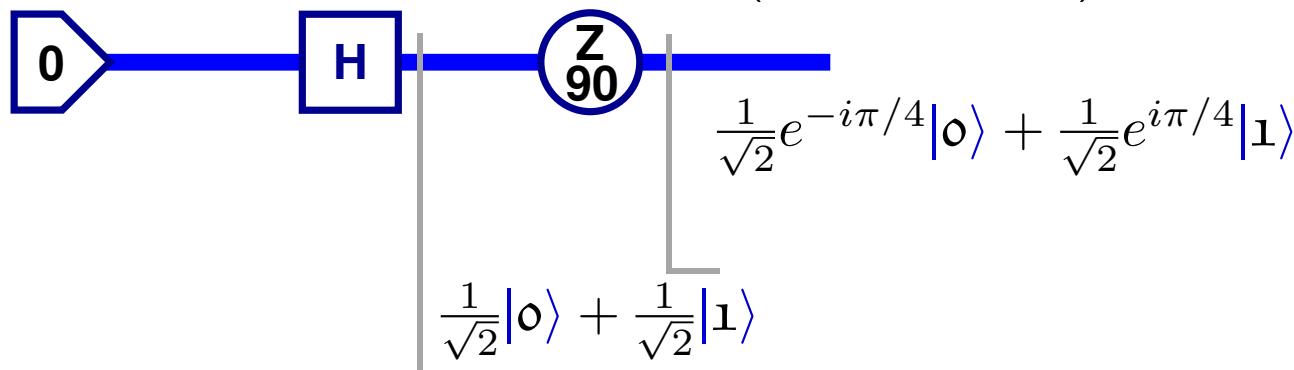


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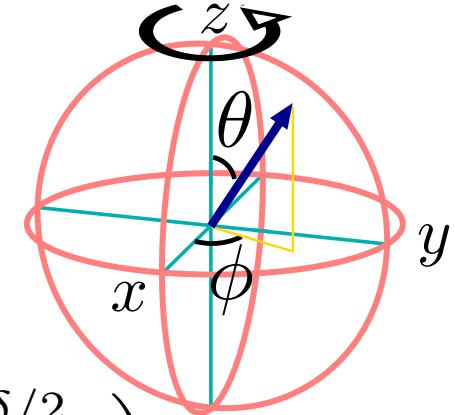
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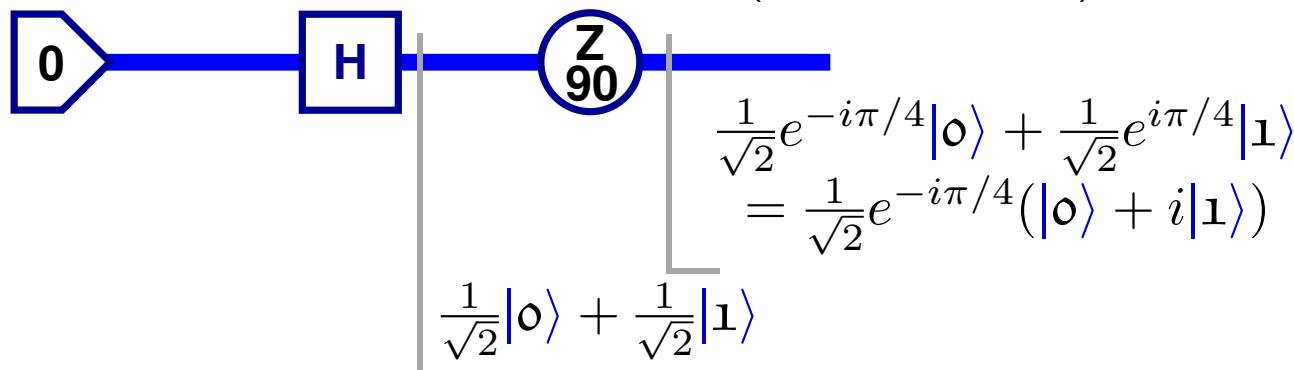


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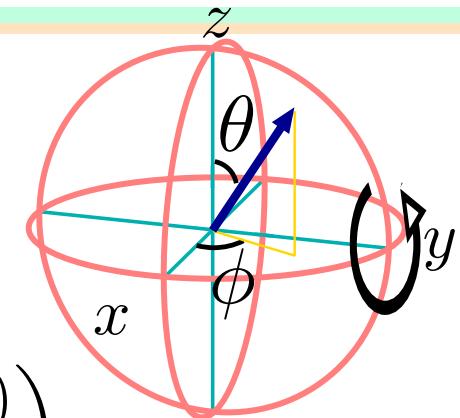
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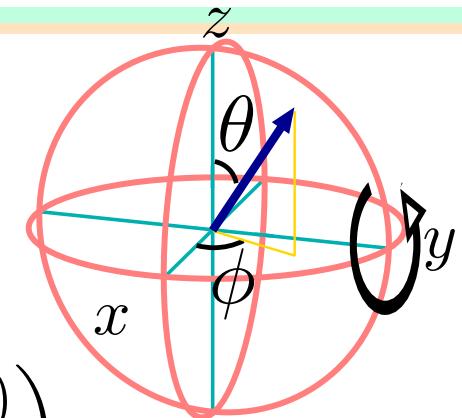
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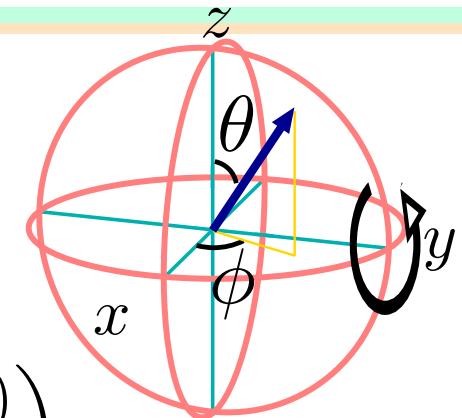
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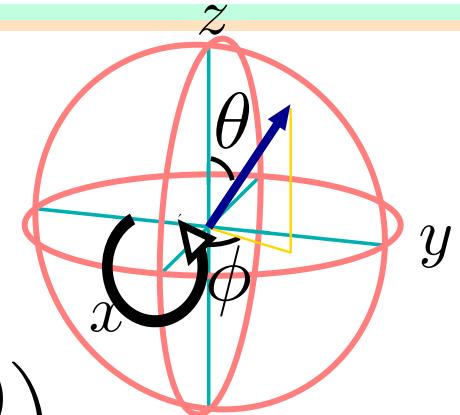
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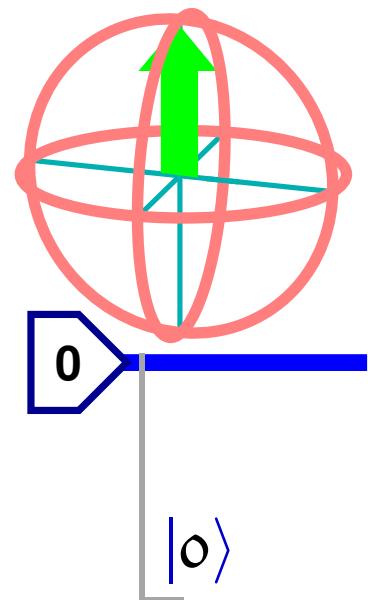
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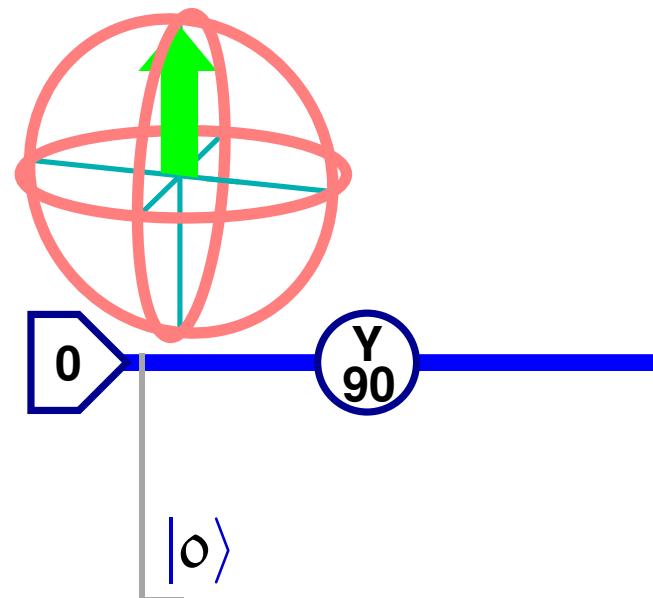
# A One-Qubit Network



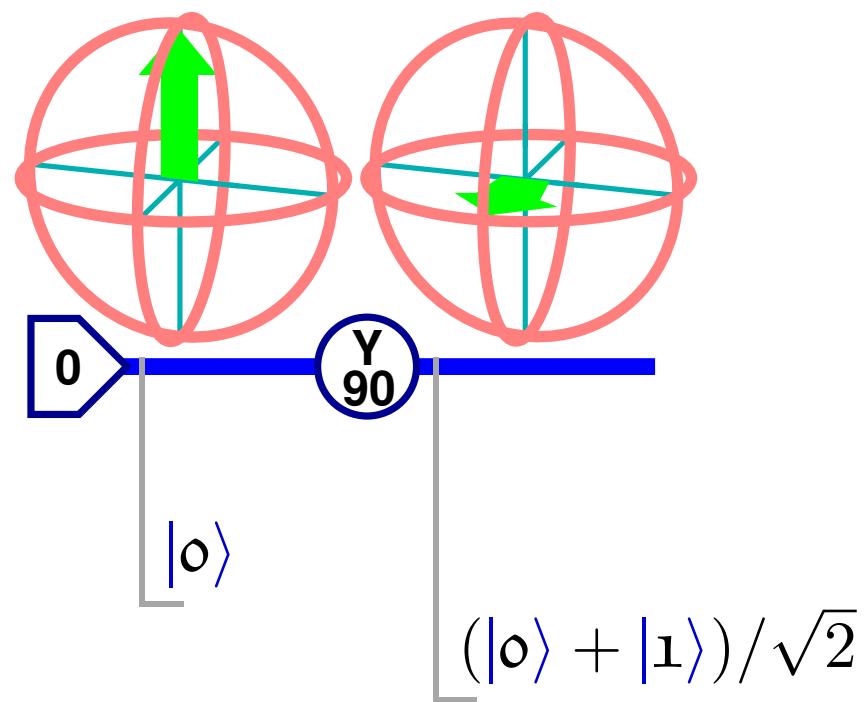
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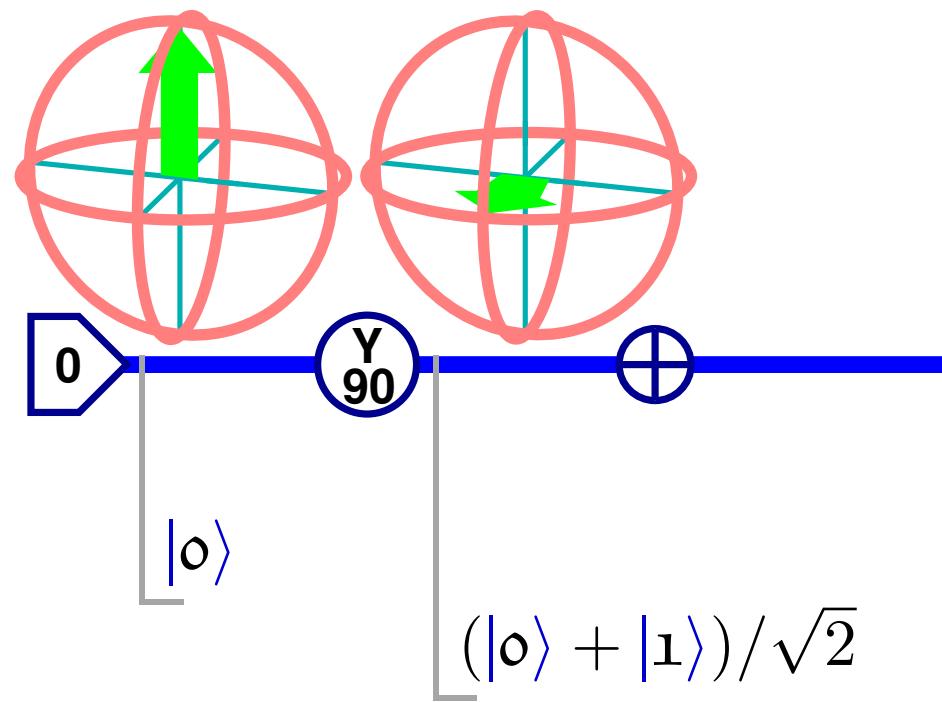
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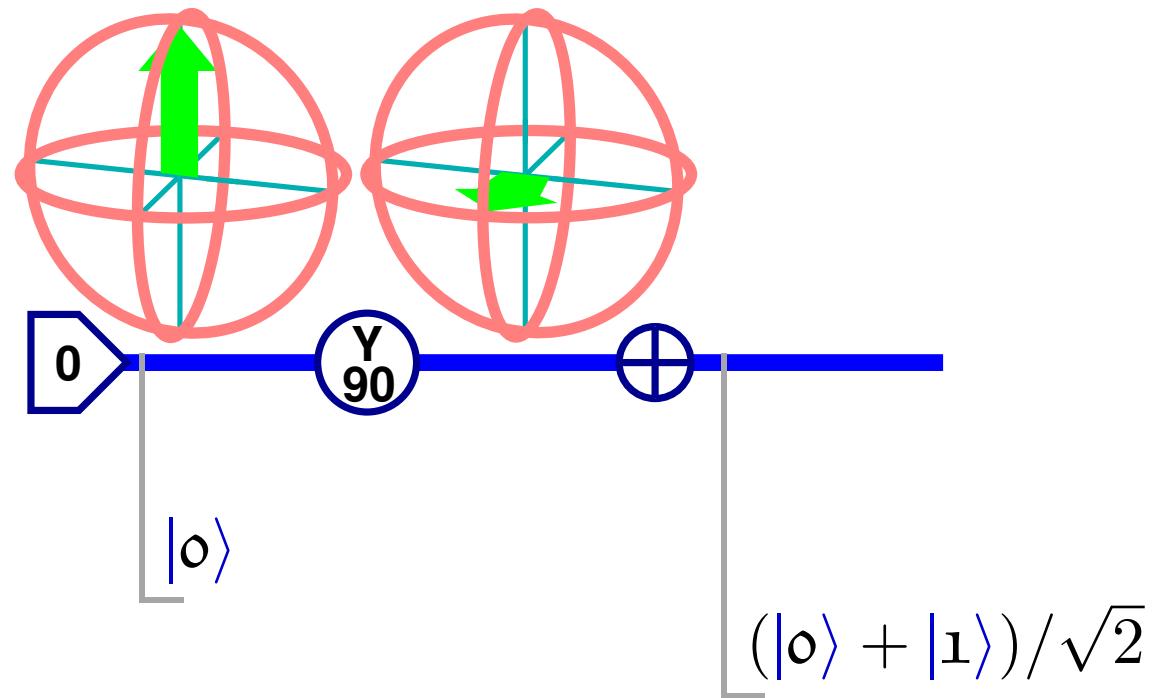
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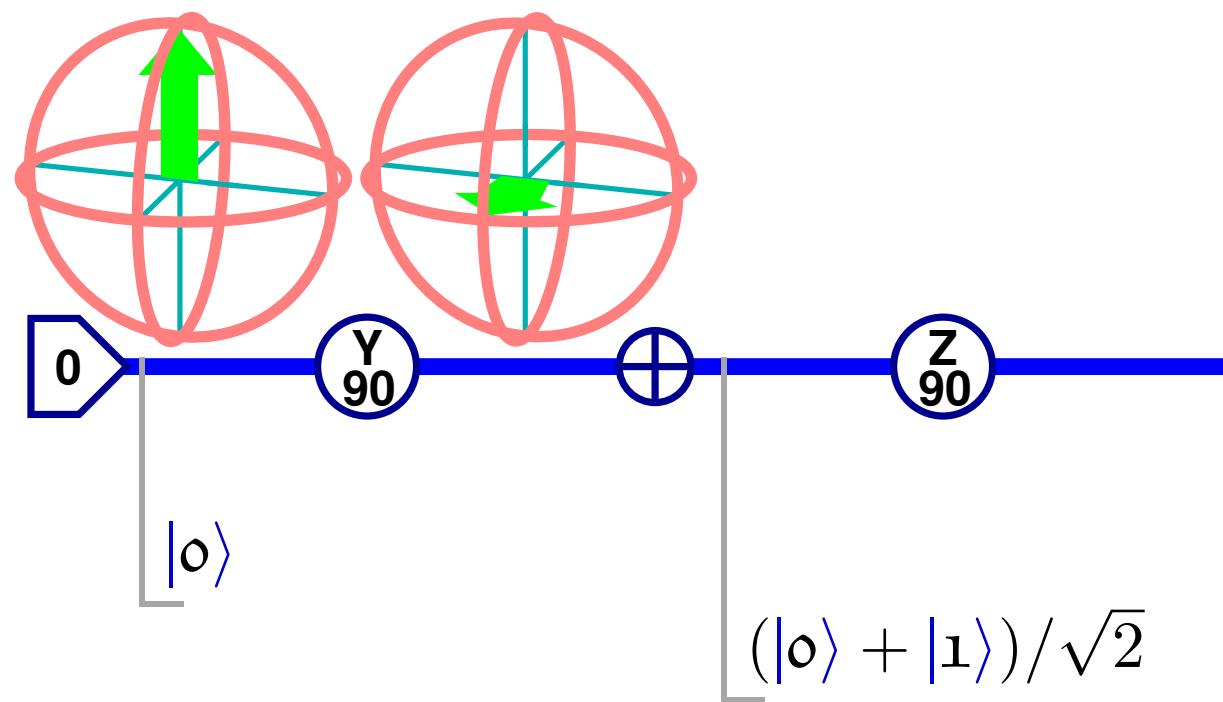
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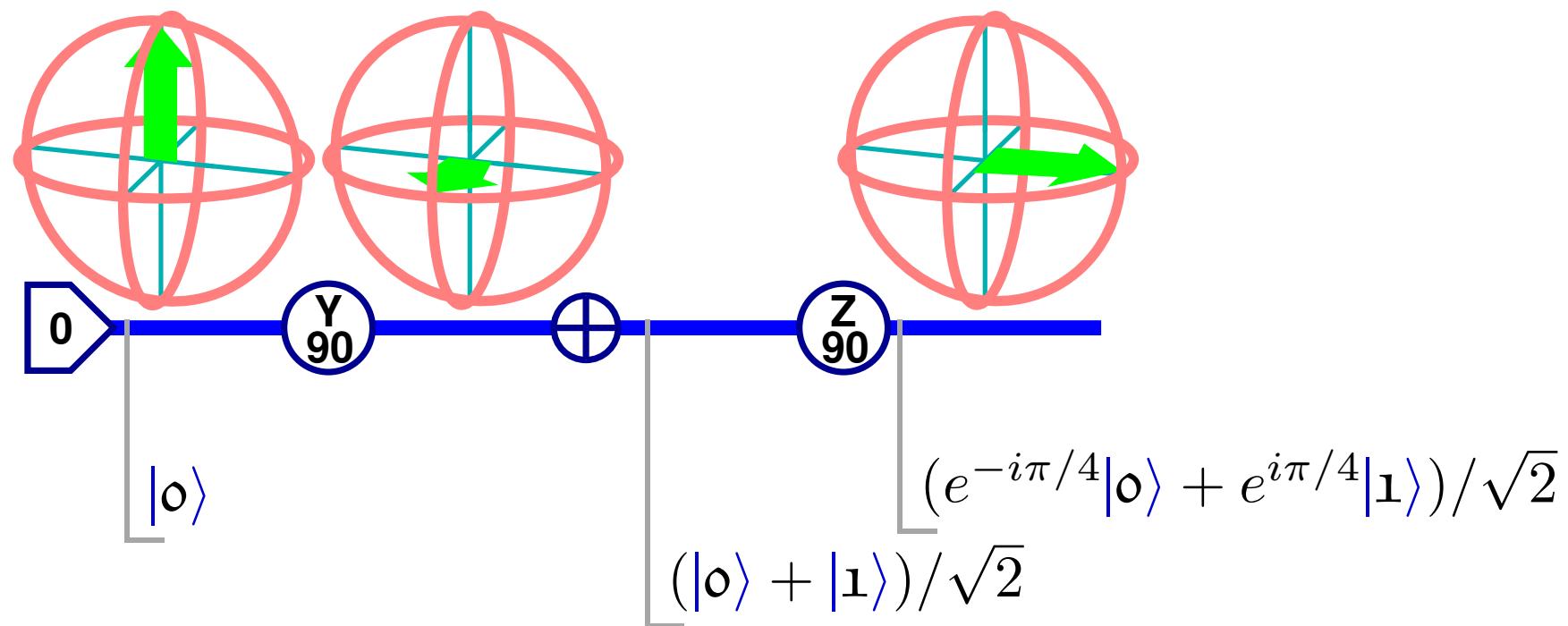
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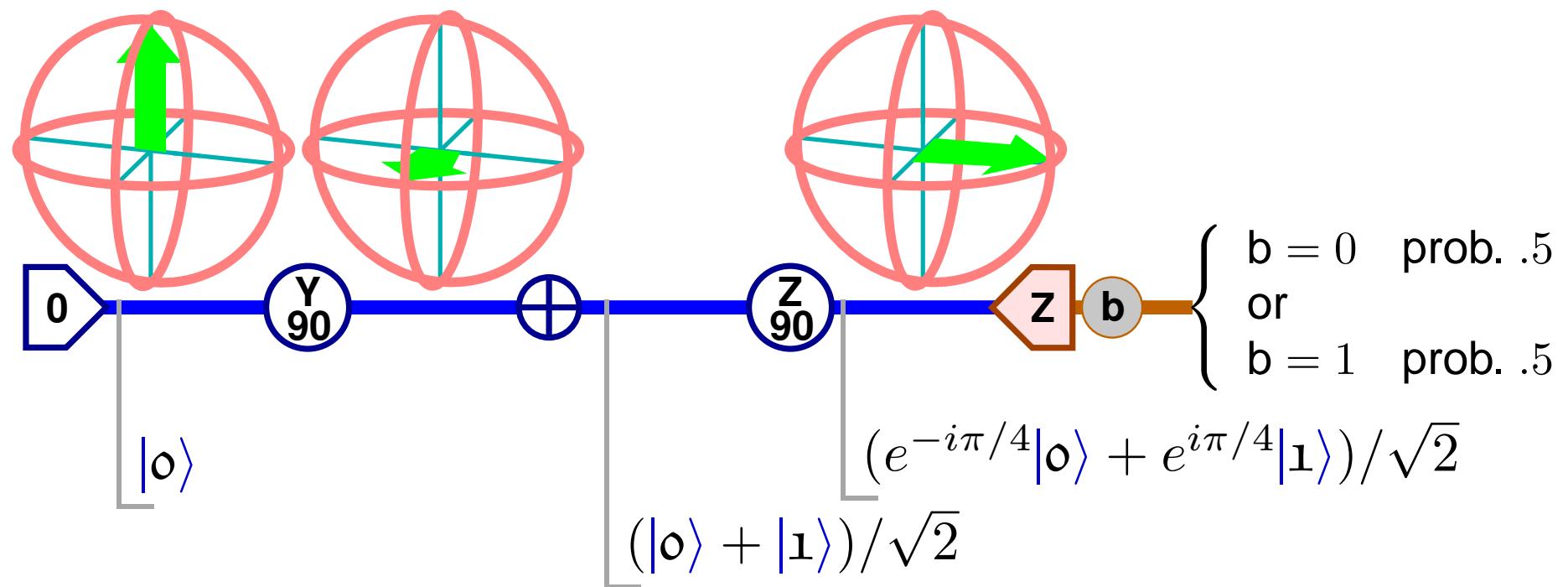
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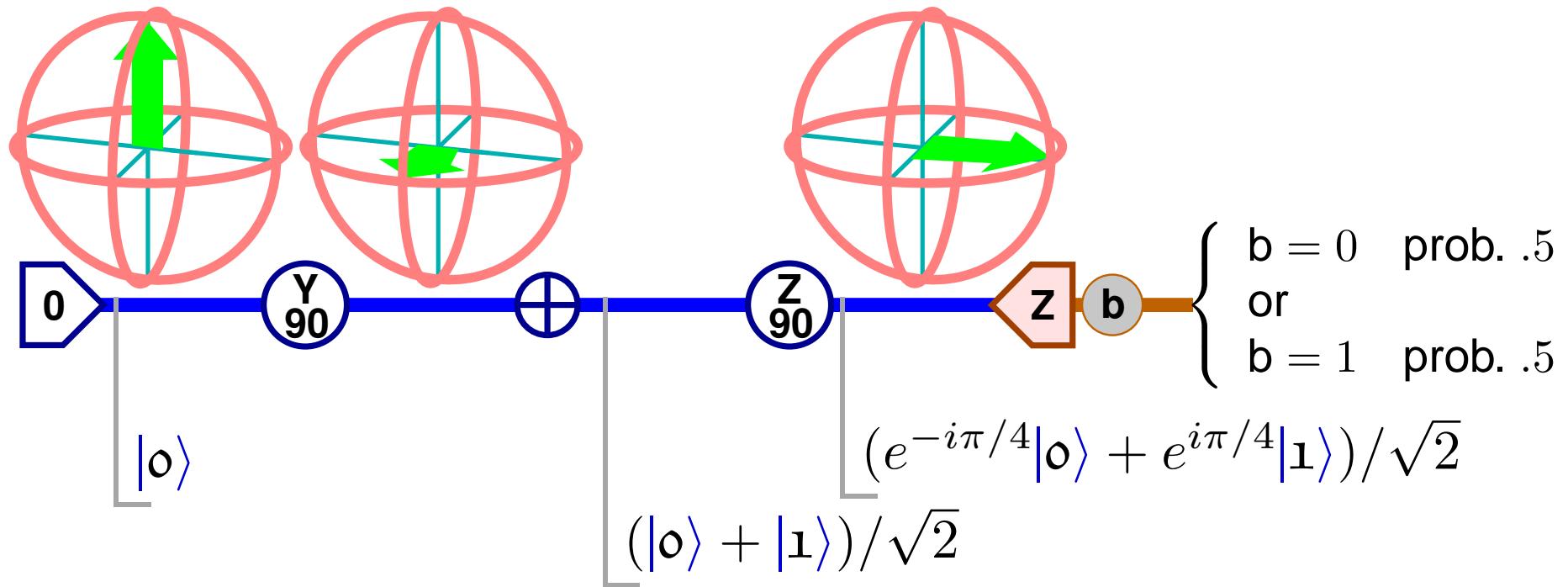
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- What rotation should be added before the measurement to guarantee that  $b = 1$ ?

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- Relationship to the first set of gates.

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For example,  $\begin{pmatrix} 1 & 1+i \\ 0 & i \end{pmatrix}^\dagger = \begin{pmatrix} 1 & 0 \\ 1-i & -i \end{pmatrix}$ .



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- The Pauli matrices form an operator basis:

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} = \frac{(a+d)}{2} \mathbb{1} + \frac{(b+c)}{2} \sigma_x + \frac{i(b-c)}{2} \sigma_y + \frac{(a-d)}{2} \sigma_z$$

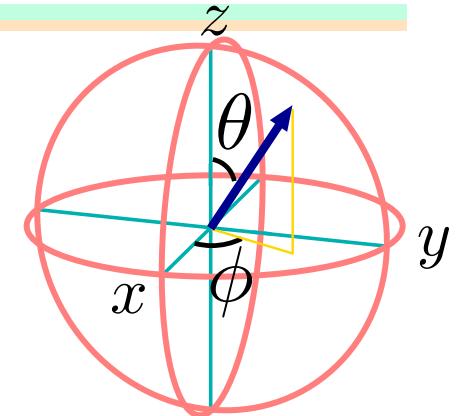


# States and the Bloch Sphere

$$e^{-i\phi/2} \cos(\theta/2) |0\rangle + e^{i\phi/2} \sin(\theta/2) |1\rangle$$

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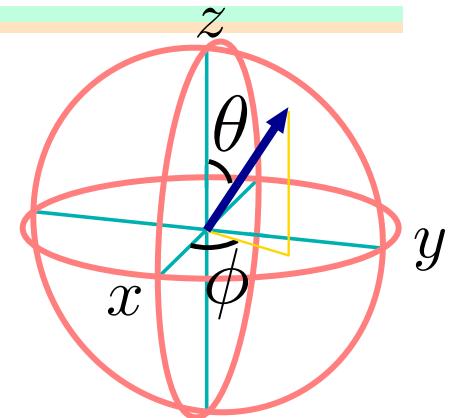
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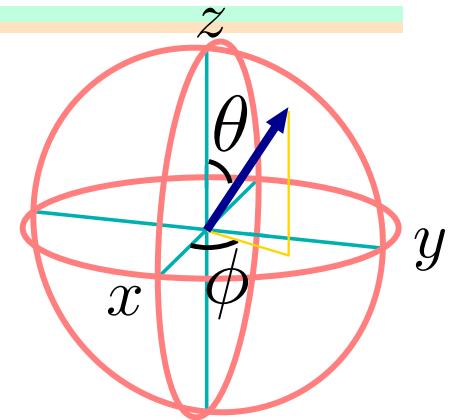
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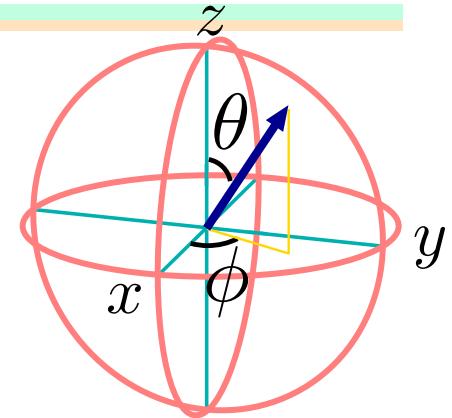
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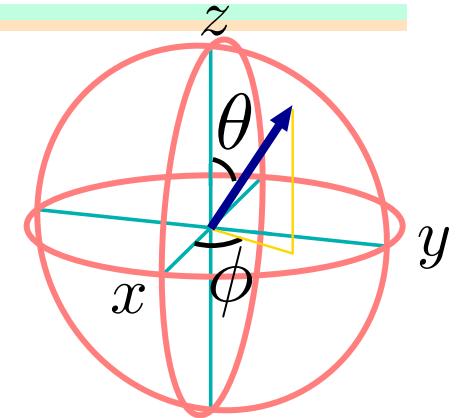
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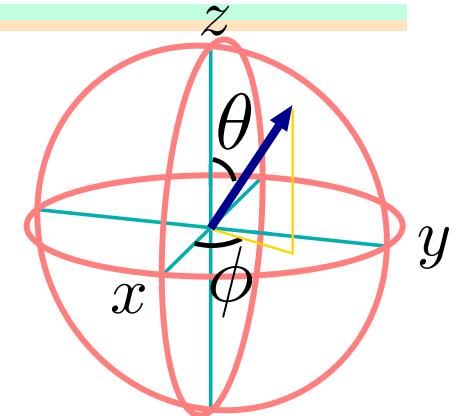
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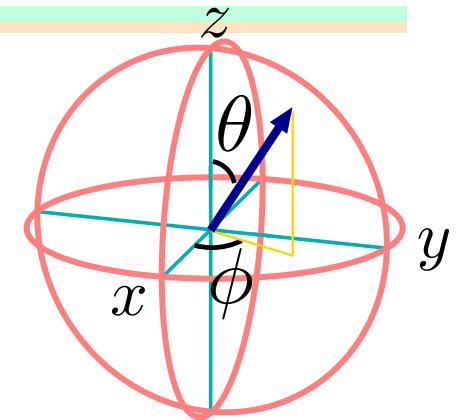
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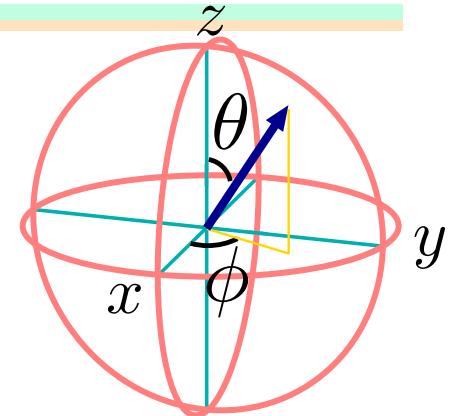
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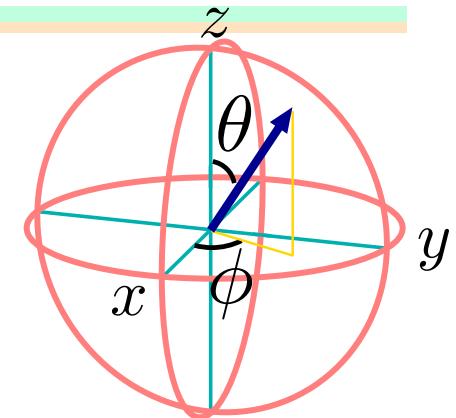
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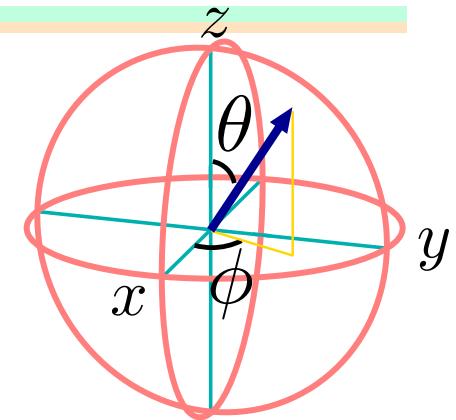
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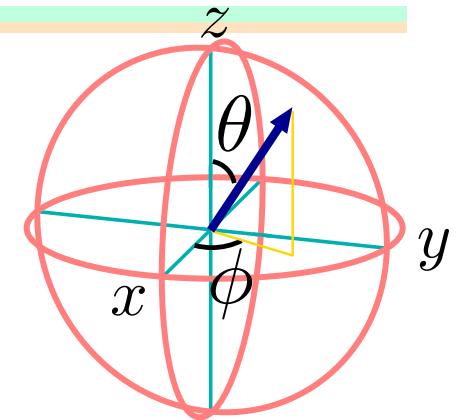
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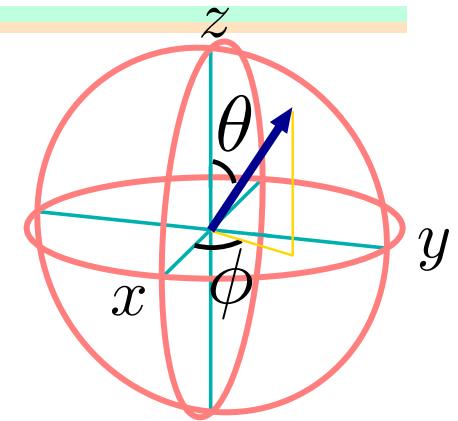
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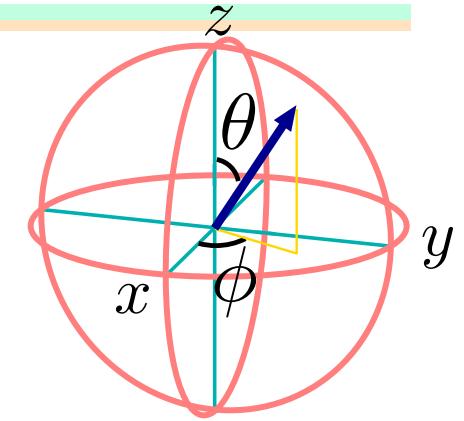
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If  $y = e^{i\delta}x$ , then  $yy^\dagger = e^{i\delta}xe^{-i\delta}x^\dagger = xx^\dagger$ .

## Examples:

$$|+\rangle \rightarrow$$

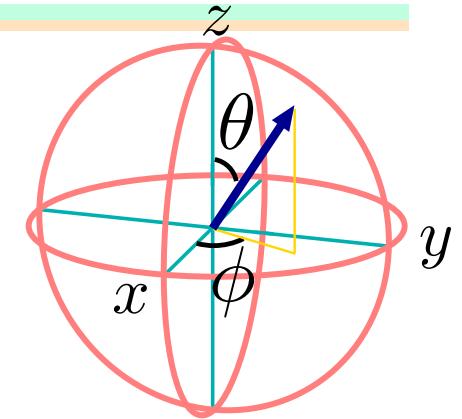
$$\left\{ \begin{array}{ccc} |0\rangle & \rightarrow & \frac{1}{2}(\mathbb{1} + \sigma_z) \\ |1\rangle & \rightarrow & \frac{1}{2}(\mathbb{1} - \sigma_z) \end{array} \right.$$

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# States and the Bloch Sphere

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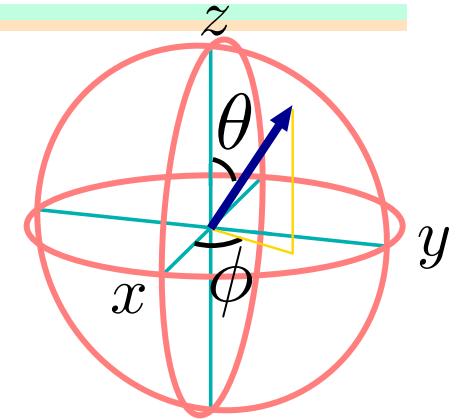
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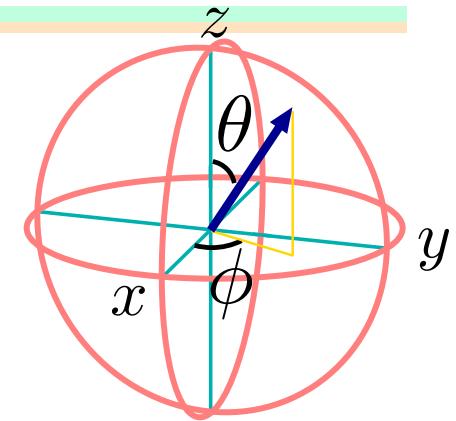
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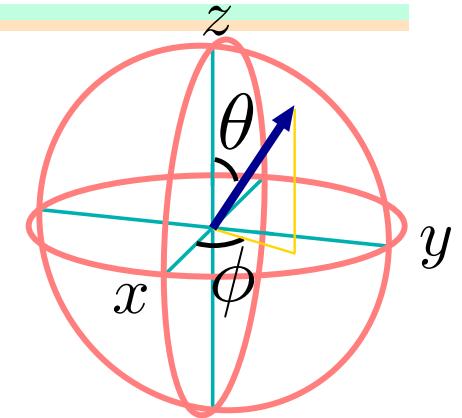
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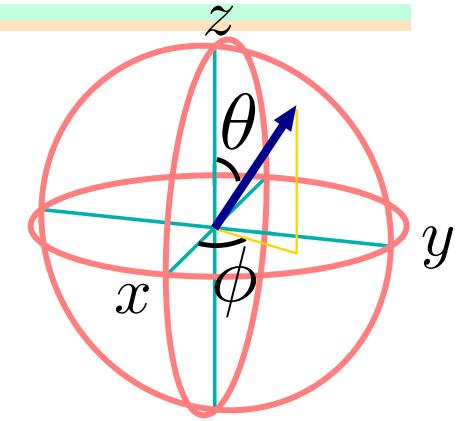
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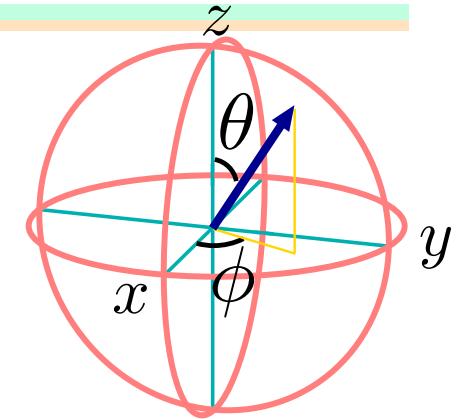
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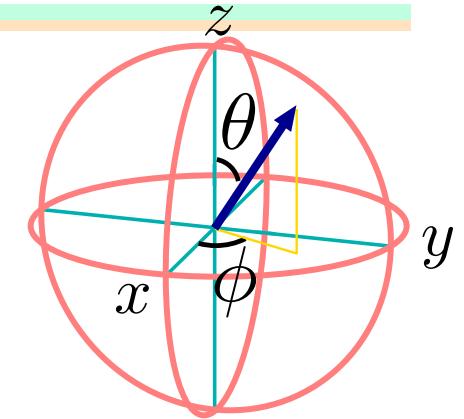
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- |                         |   |
|-------------------------|---|
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|-------------------------|---|

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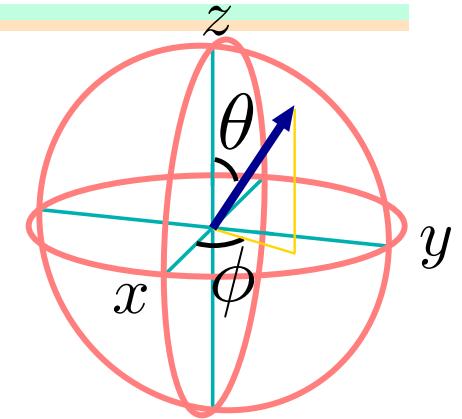
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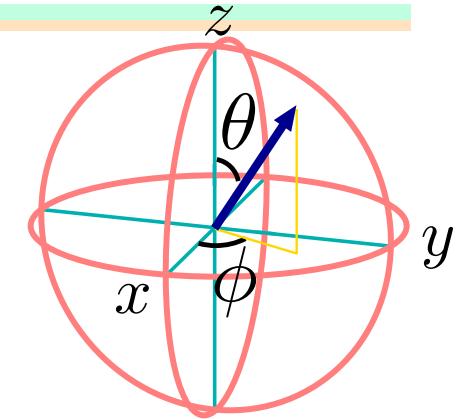
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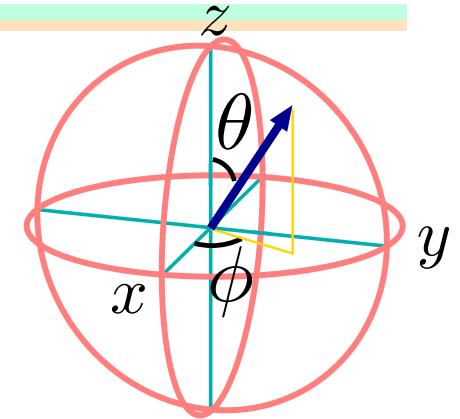
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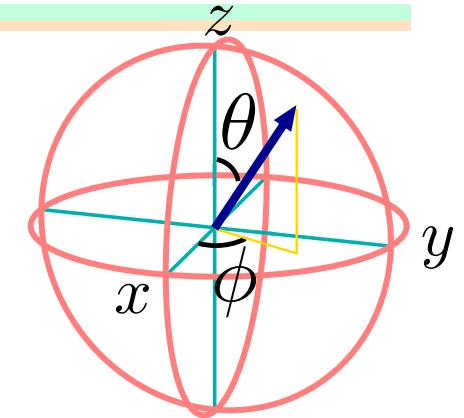
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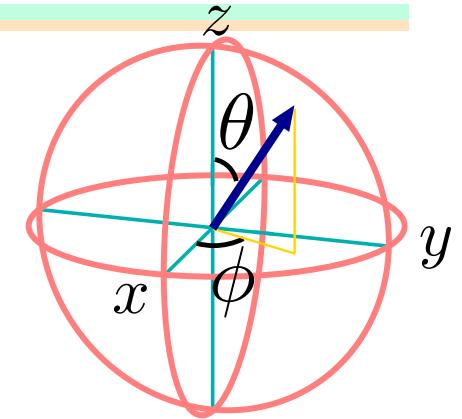
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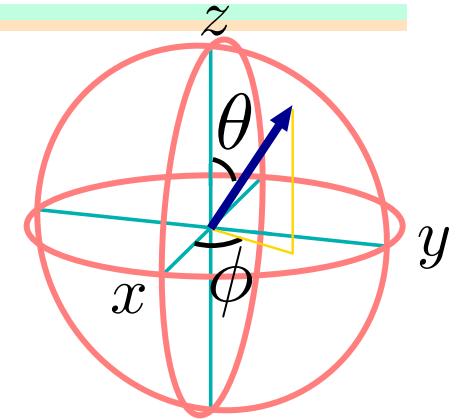
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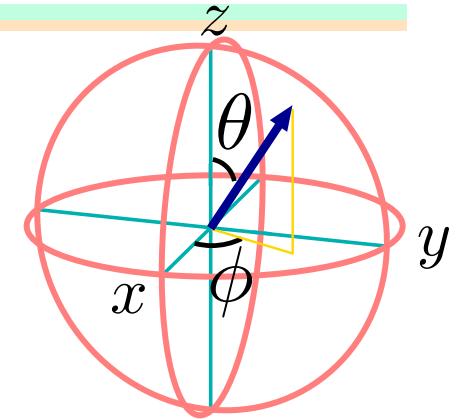
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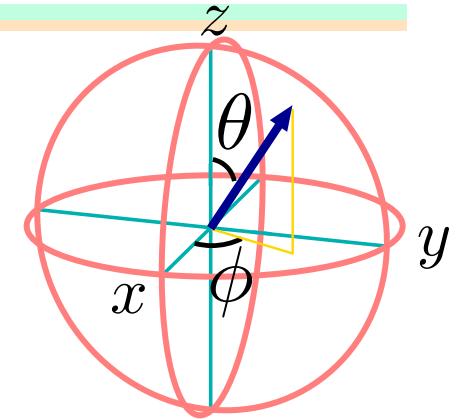
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$$|-i\rangle = \frac{1}{\sqrt{2}}(|0\rangle - i|1\rangle) \rightarrow \begin{cases} |0\rangle & \rightarrow \frac{1}{2}(\mathbb{1} + \sigma_z) \\ |+\rangle & \rightarrow \frac{1}{2}(\mathbb{1} + \sigma_x) \\ |+i\rangle & \rightarrow \frac{1}{2}(\mathbb{1} + \sigma_y) \end{cases} \quad \begin{cases} |1\rangle & \rightarrow \frac{1}{2}(\mathbb{1} - \sigma_z) \\ |-\rangle & \rightarrow \frac{1}{2}(\mathbb{1} - \sigma_x) \\ |-i\rangle & \rightarrow \frac{1}{2}(\mathbb{1} - \sigma_y) \end{cases}$$

$$\begin{aligned} \frac{1}{2} \begin{pmatrix} 1 \\ -i \end{pmatrix} (1, i) &= \begin{pmatrix} 1 & i \\ -i & 1 \end{pmatrix} = \frac{1}{2} \left( \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \right) \\ &= \frac{1}{2}(\mathbb{1} - \sigma_y) \end{aligned}$$



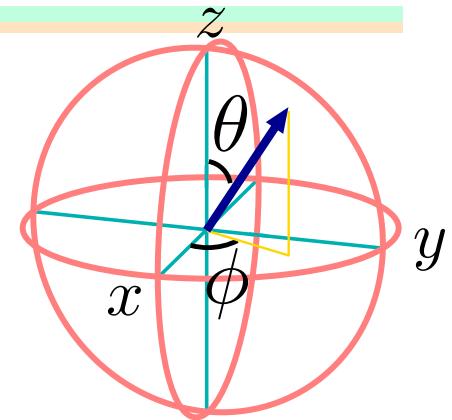
# States and the Bloch Sphere

$$e^{-i\phi/2} \cos(\theta/2) |0\rangle + e^{i\phi/2} \sin(\theta/2) |1\rangle$$

- The *density matrix*  $\rho$  for state  $x = \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$  is

$$\rho = xx^\dagger = \begin{pmatrix} \alpha \\ \beta \end{pmatrix} (\bar{\alpha}, \bar{\beta}) = \begin{pmatrix} \alpha\bar{\alpha} & \alpha\bar{\beta} \\ \beta\bar{\alpha} & \beta\bar{\beta} \end{pmatrix}$$

- $\rho$  represents the accessible information about the state.  
If  $y = e^{i\delta}x$ , then  $yy^\dagger = e^{i\delta}xe^{-i\delta}x^\dagger = xx^\dagger$ .



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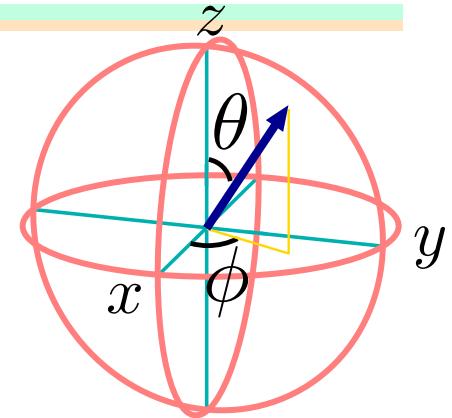
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If  $y = e^{i\delta}x$ , then  $yy^\dagger = e^{i\delta}xe^{-i\delta}x^\dagger = xx^\dagger$ .
- $|\psi\rangle$  corresponds to  $\hat{u}$  on the Bloch sphere if and only if the density matrix  $\rho$  for  $|\psi\rangle$  is given by

$$\rho = \frac{1}{2}(1 + \hat{u} \cdot \vec{\sigma}) = \frac{1}{2}(1 + u_x\sigma_x + u_y\sigma_y + u_z\sigma_z)$$



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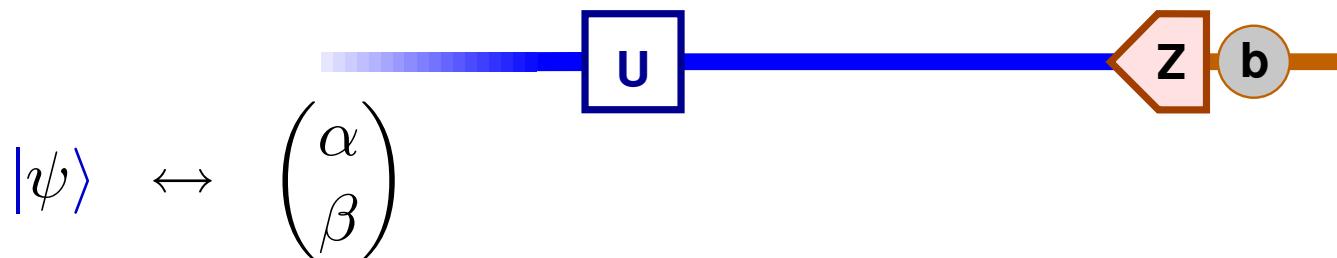
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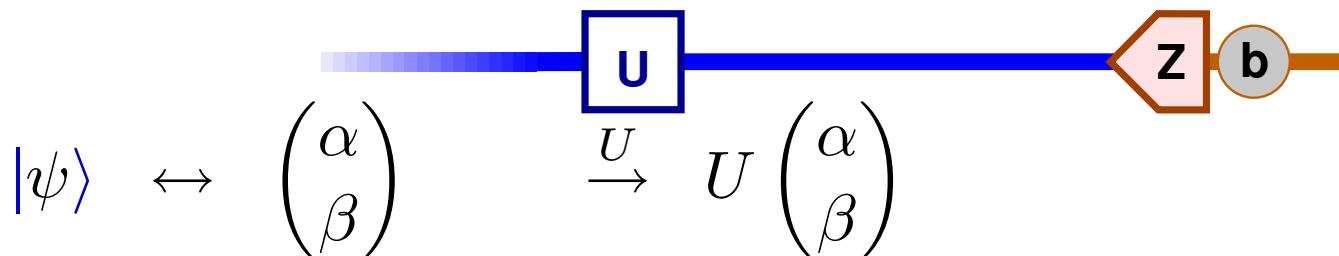
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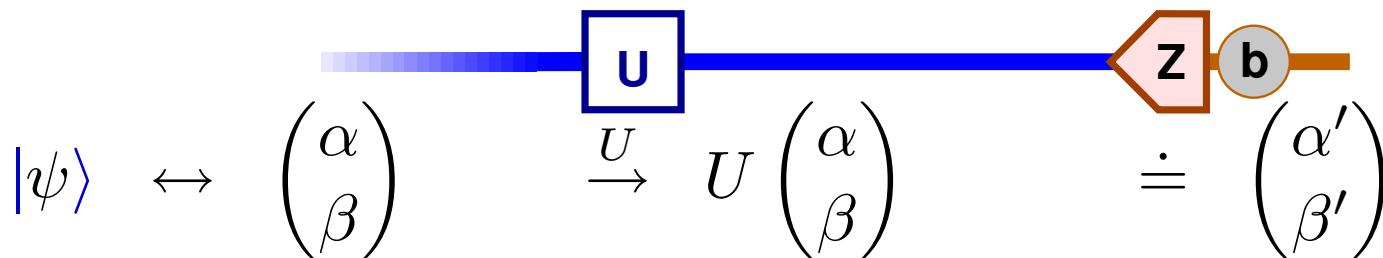
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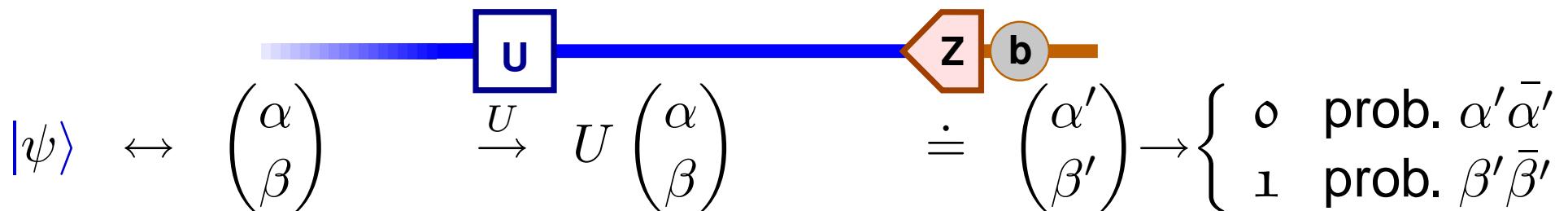
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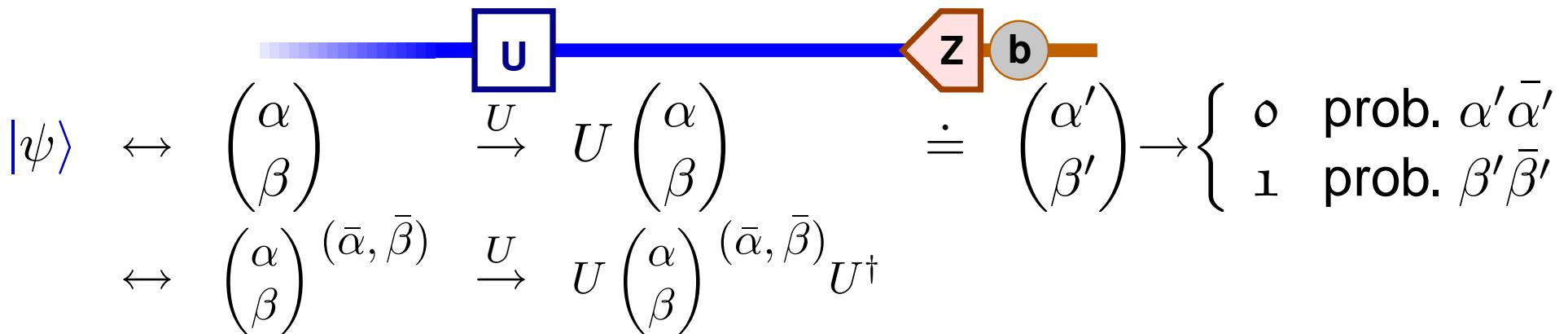
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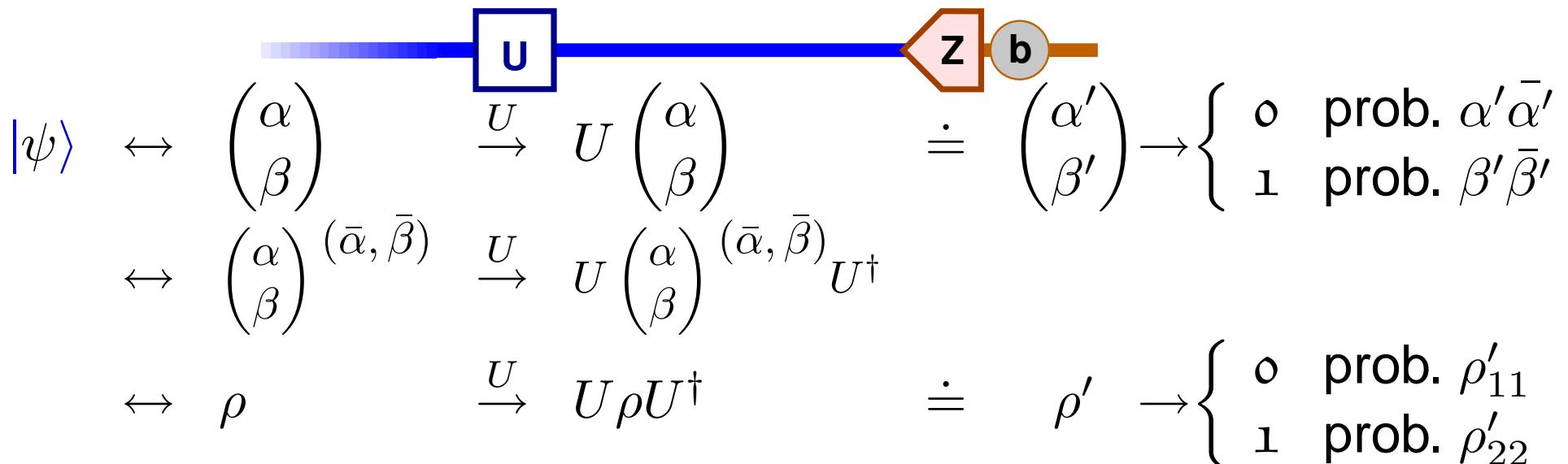
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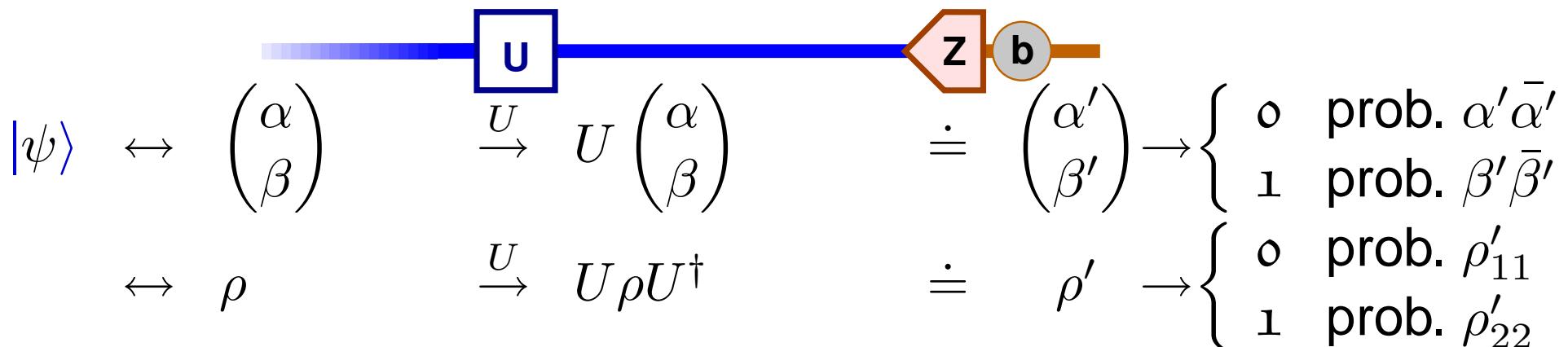
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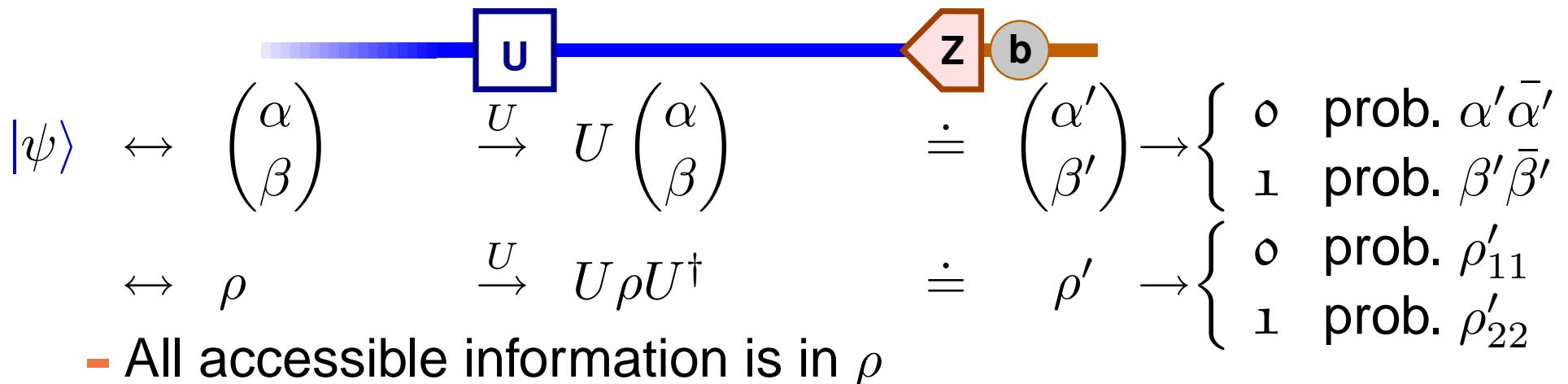
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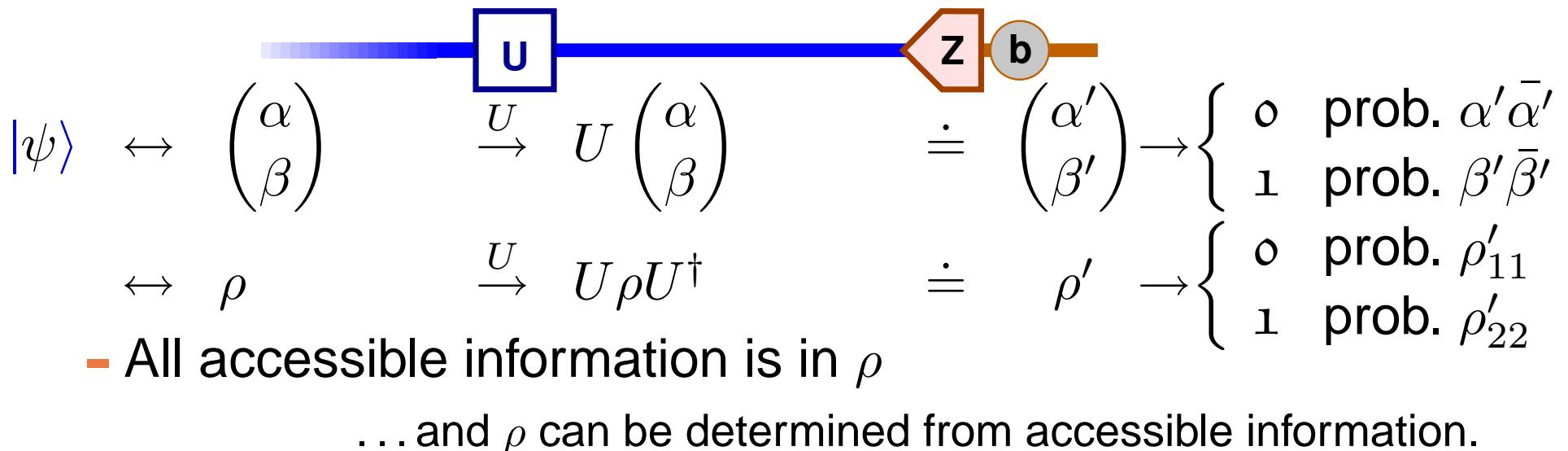
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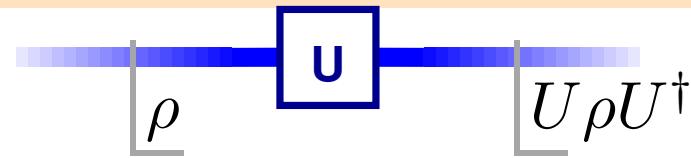
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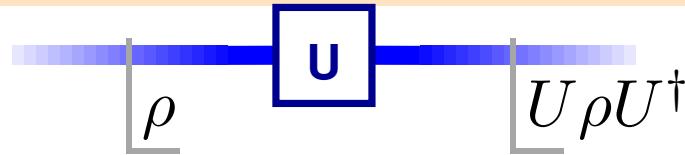
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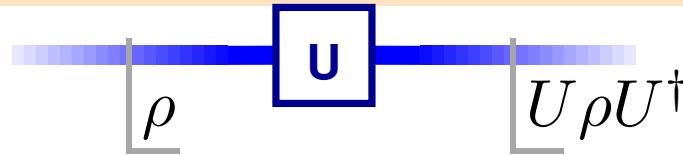


# Conjugation



- Applying  $U$  conjugates density matrix  $\rho$  by  $U$ .

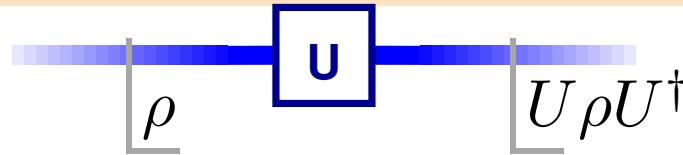
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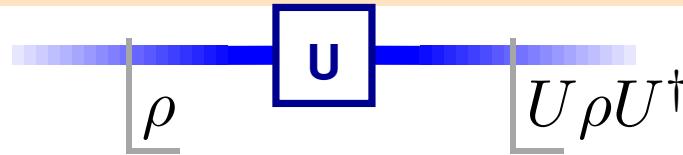
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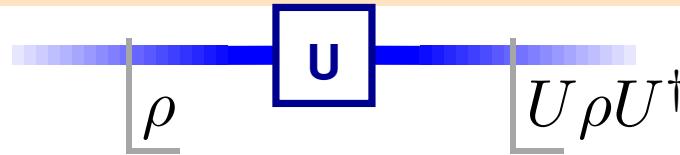
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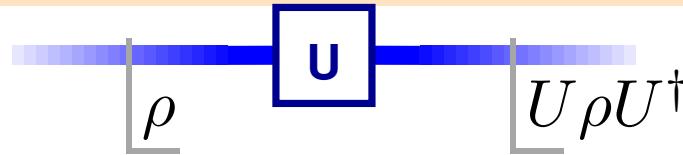
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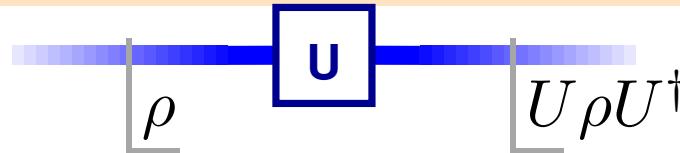
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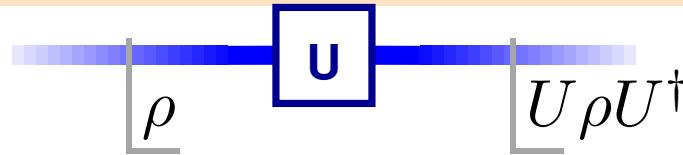


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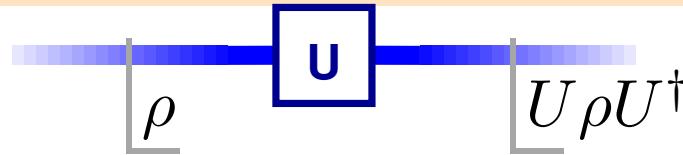


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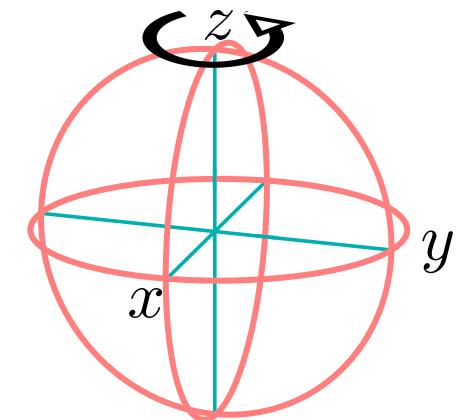


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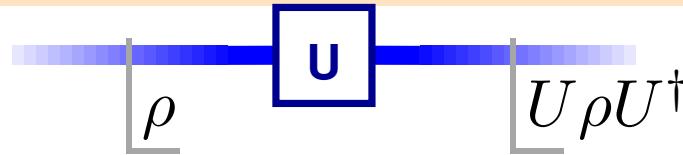
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- Simplify:



# Conjugation

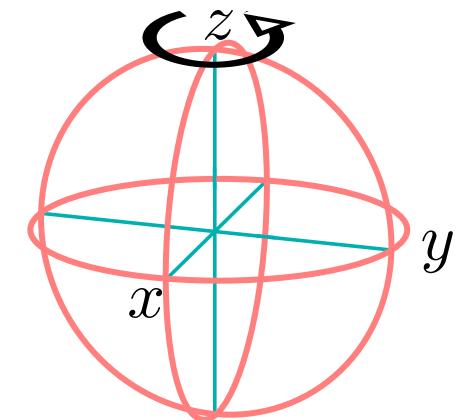
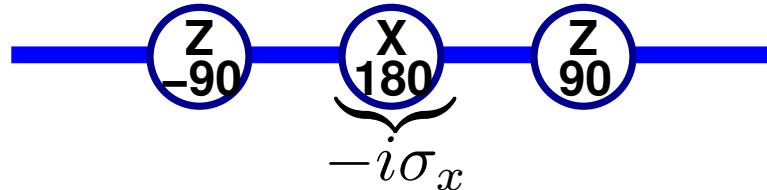


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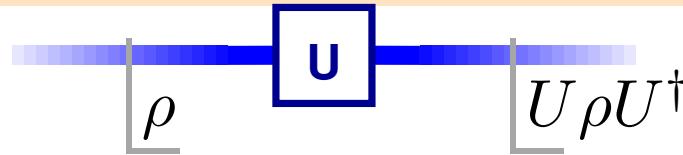
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# Conjugation

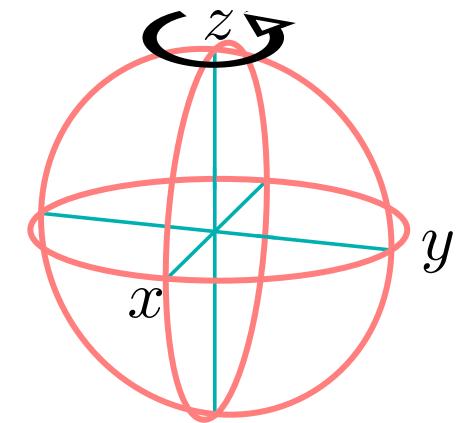
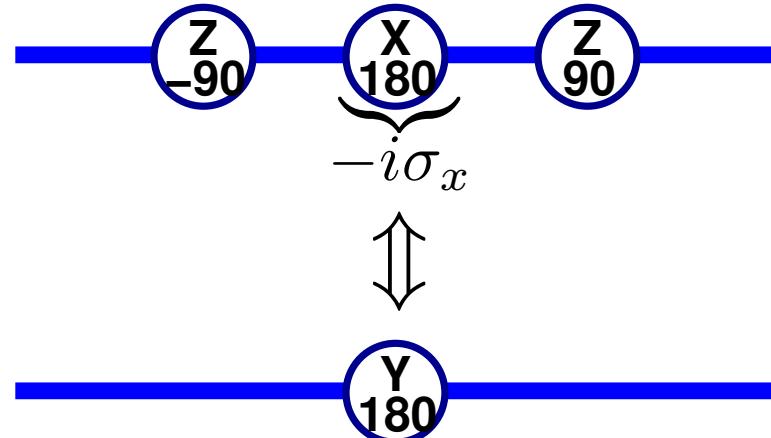


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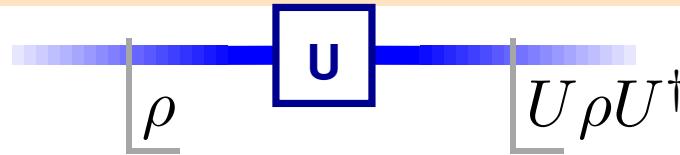
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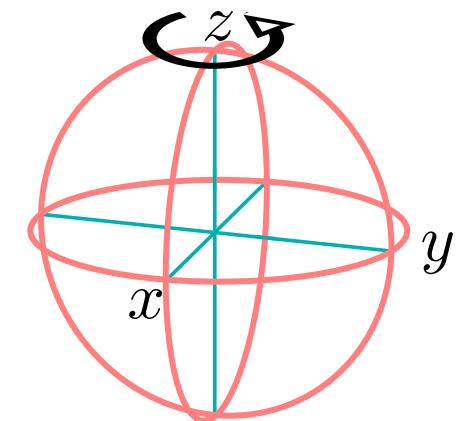


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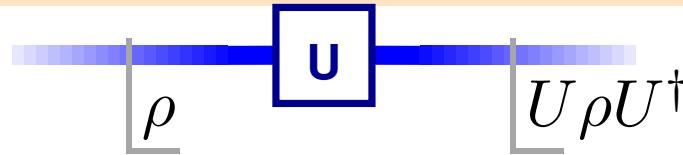
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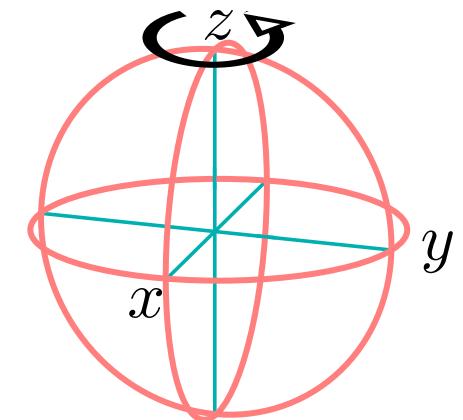
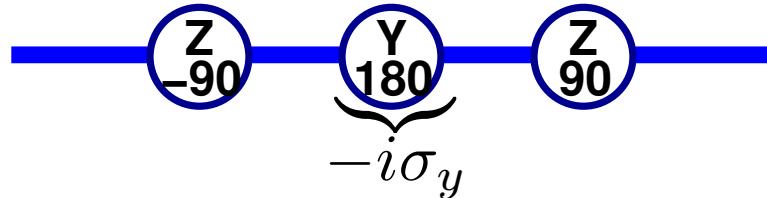


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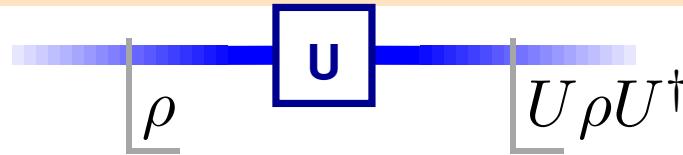
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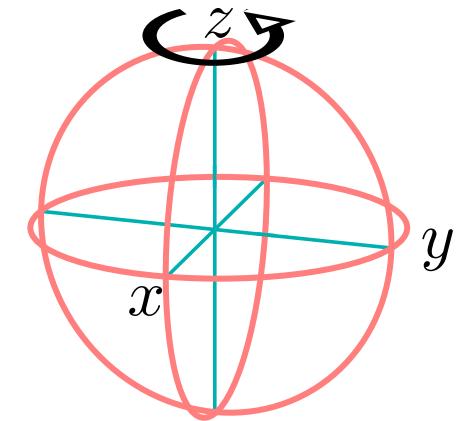
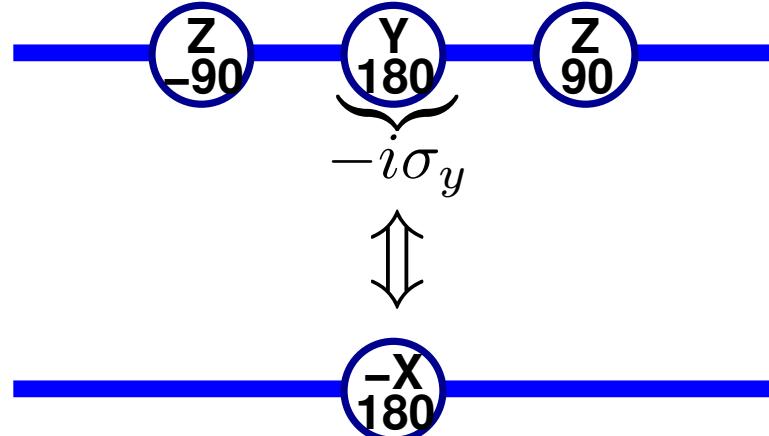


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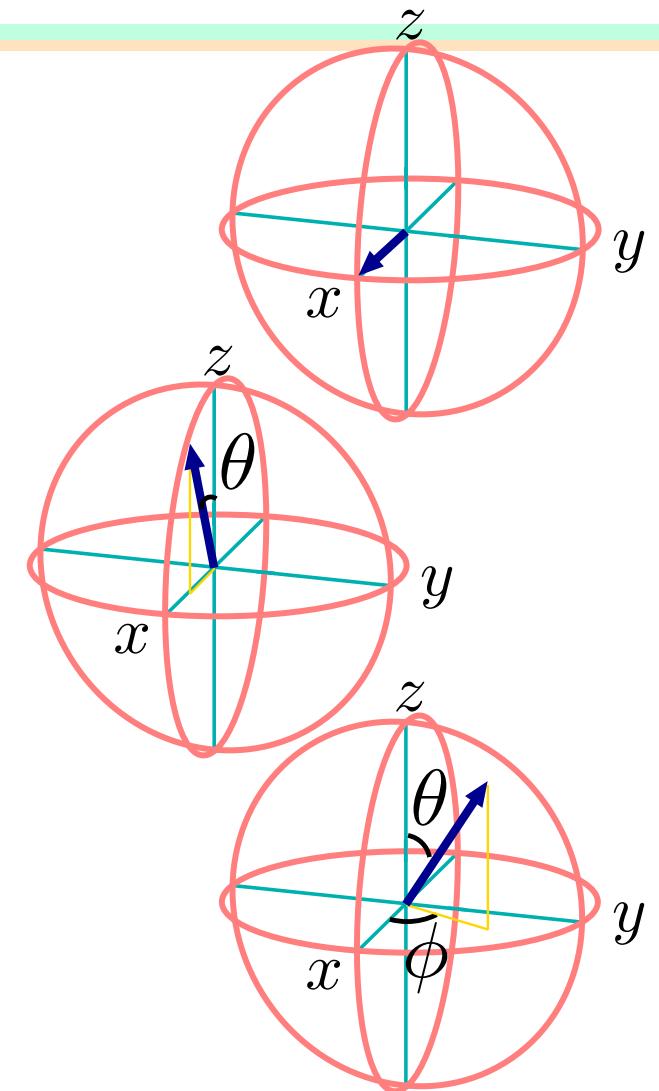
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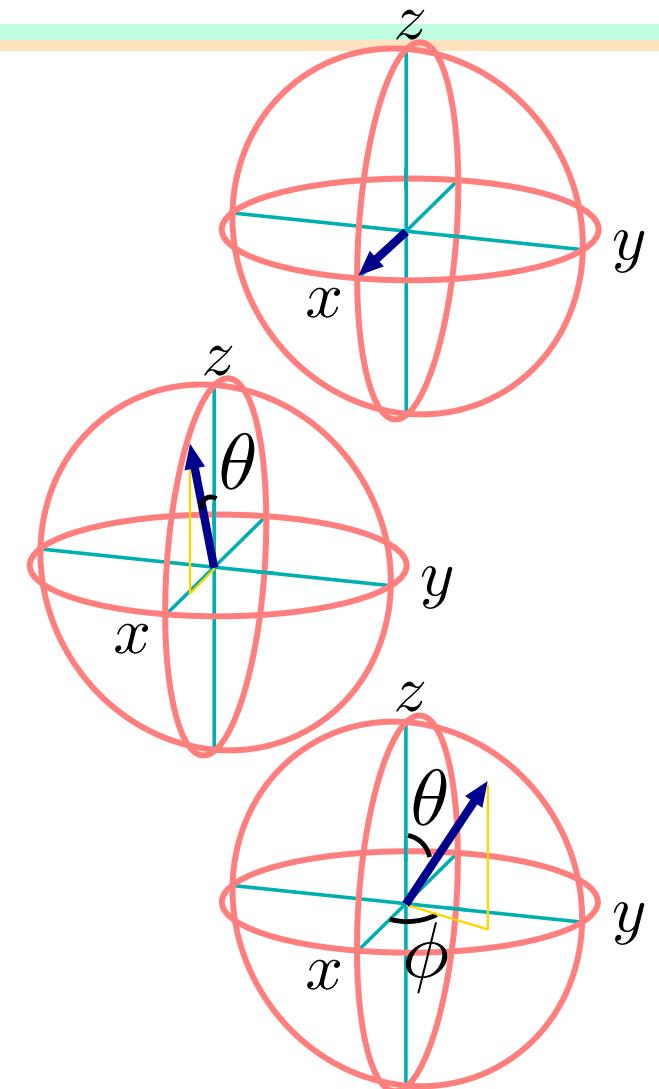
# More Conjugation

- 180° rotation around an arbitrary axis.



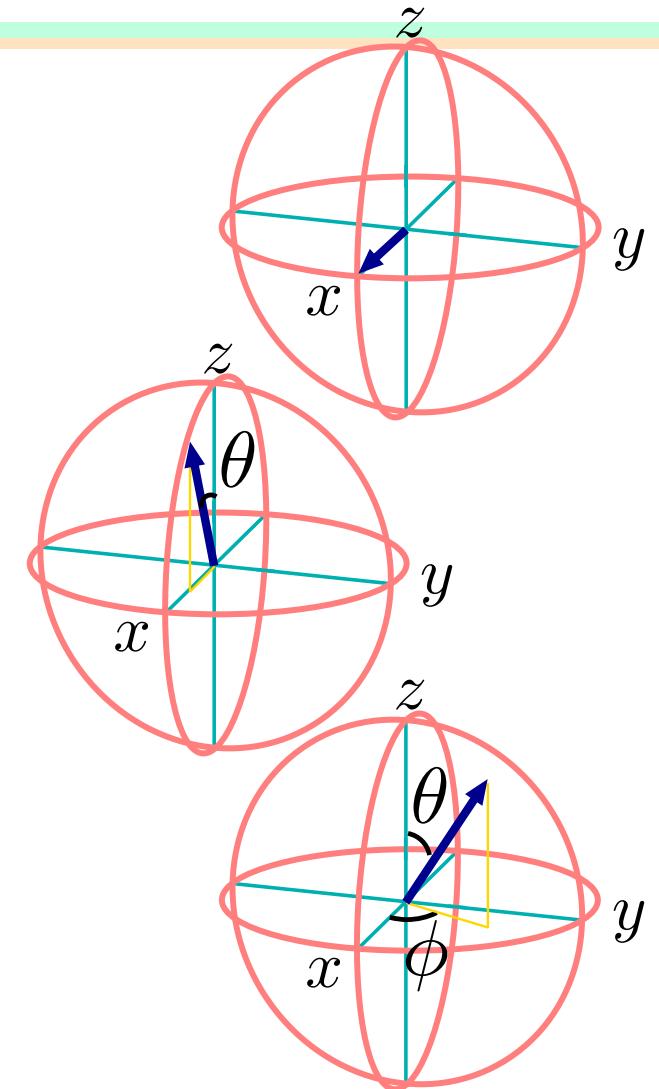
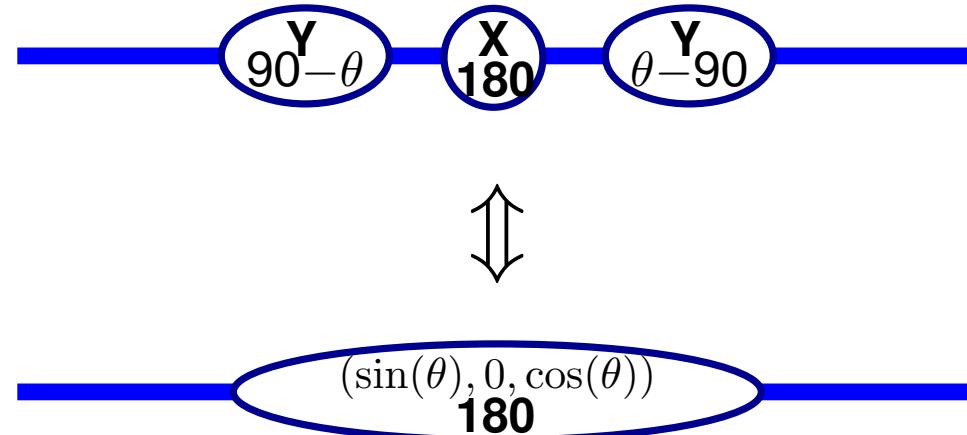
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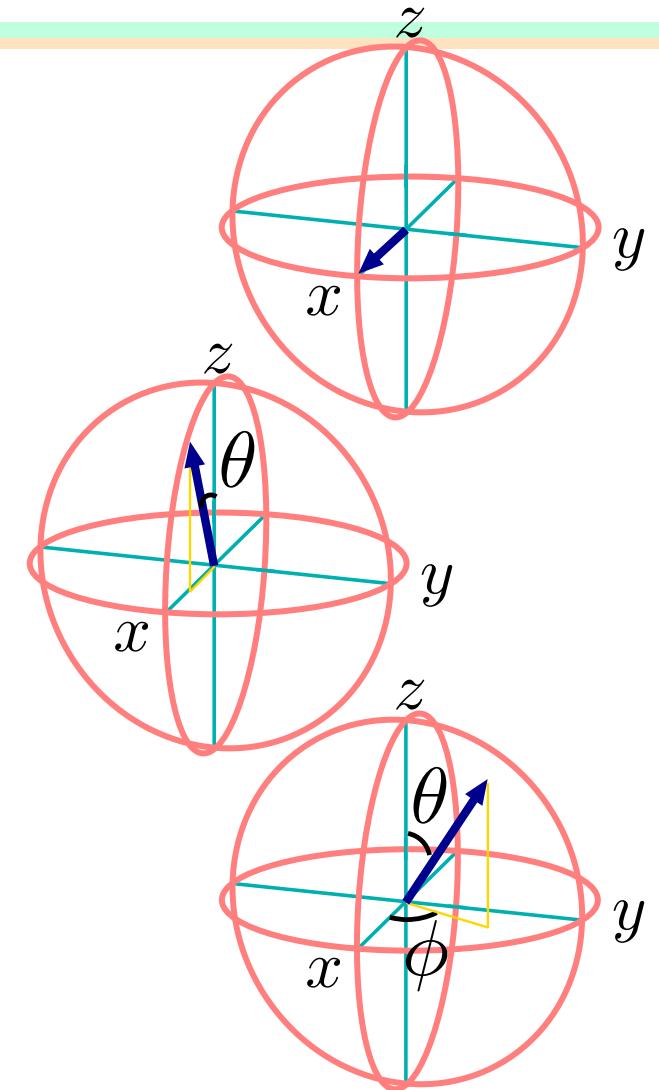
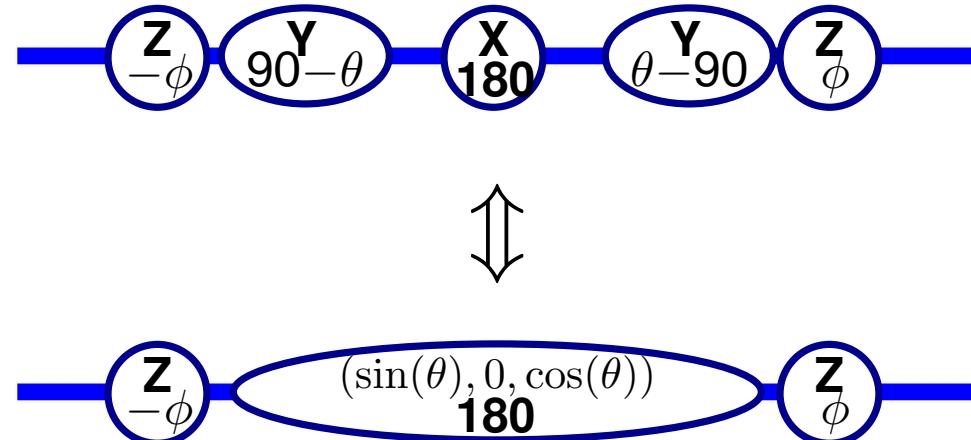
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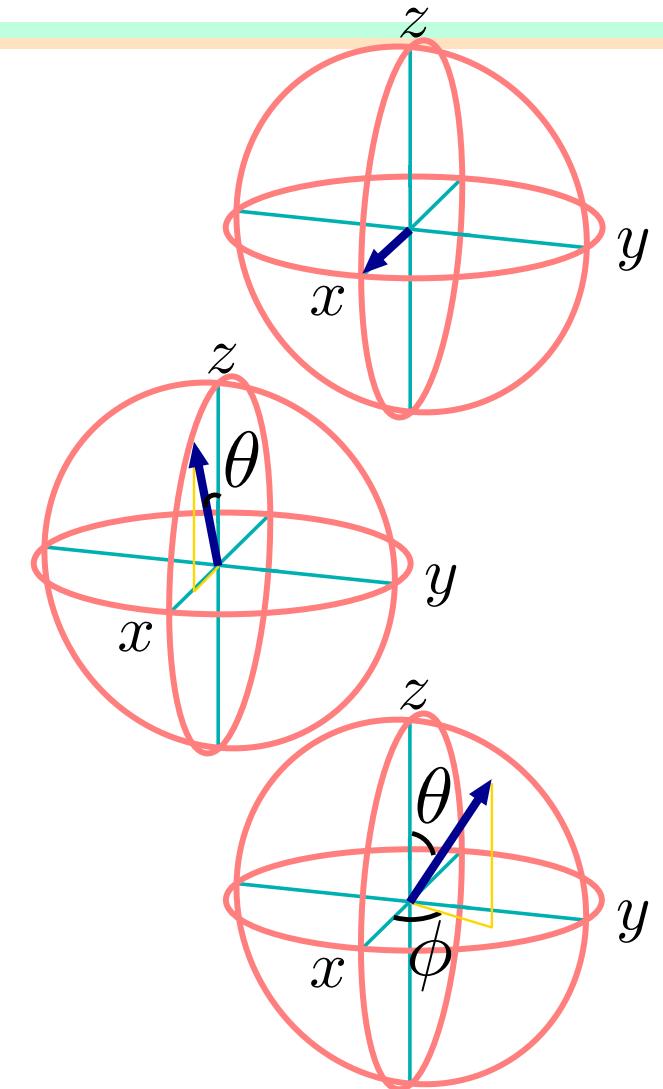
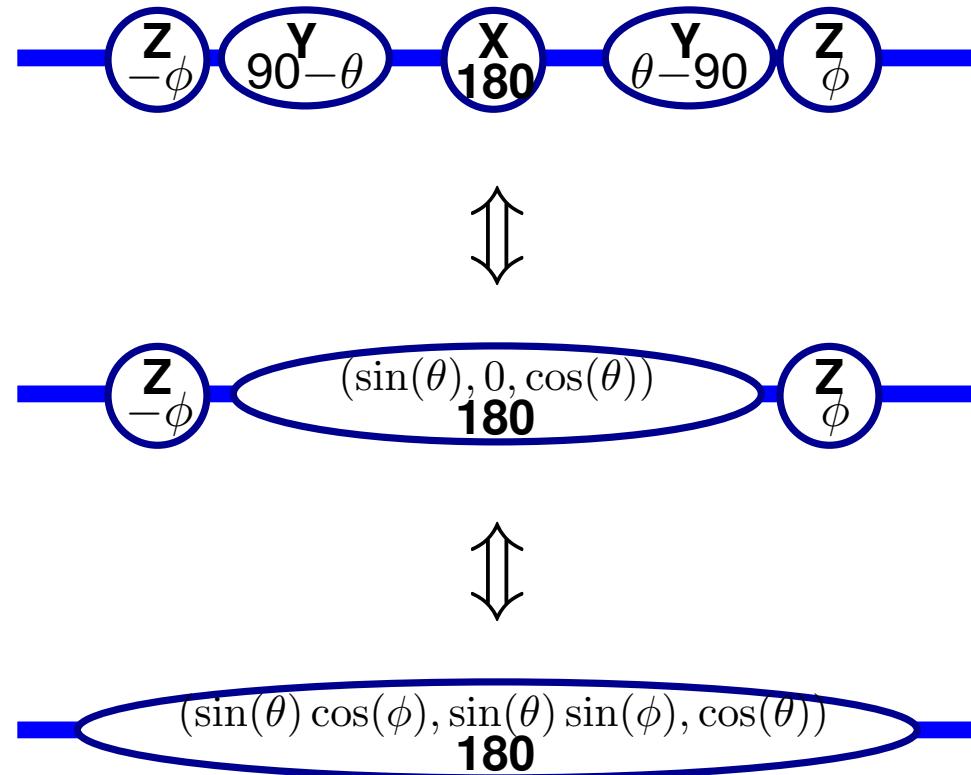
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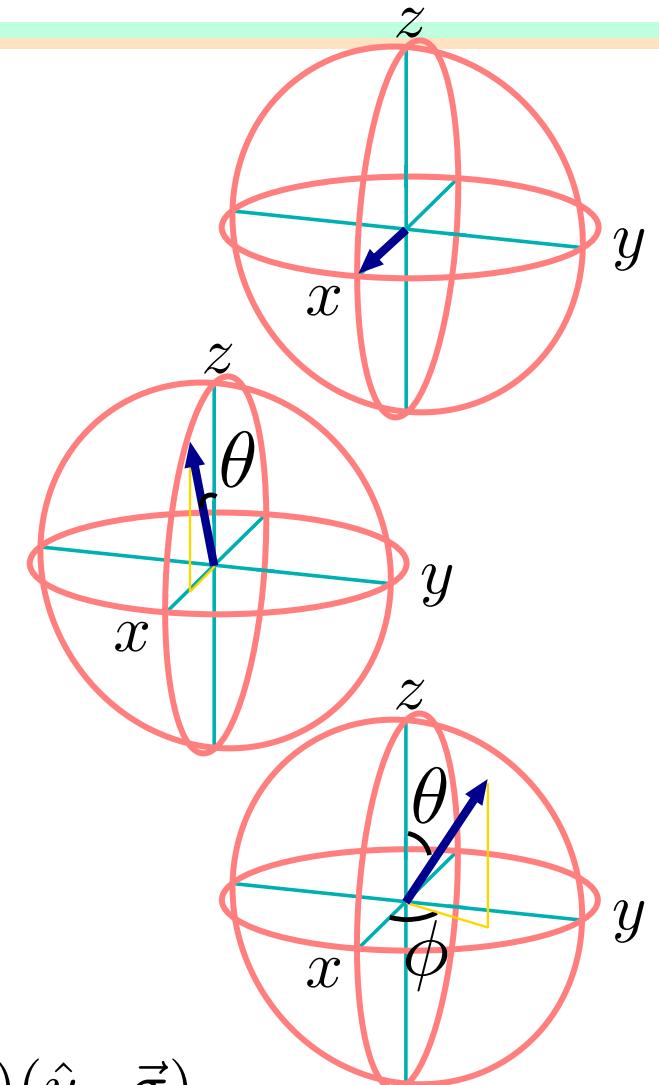
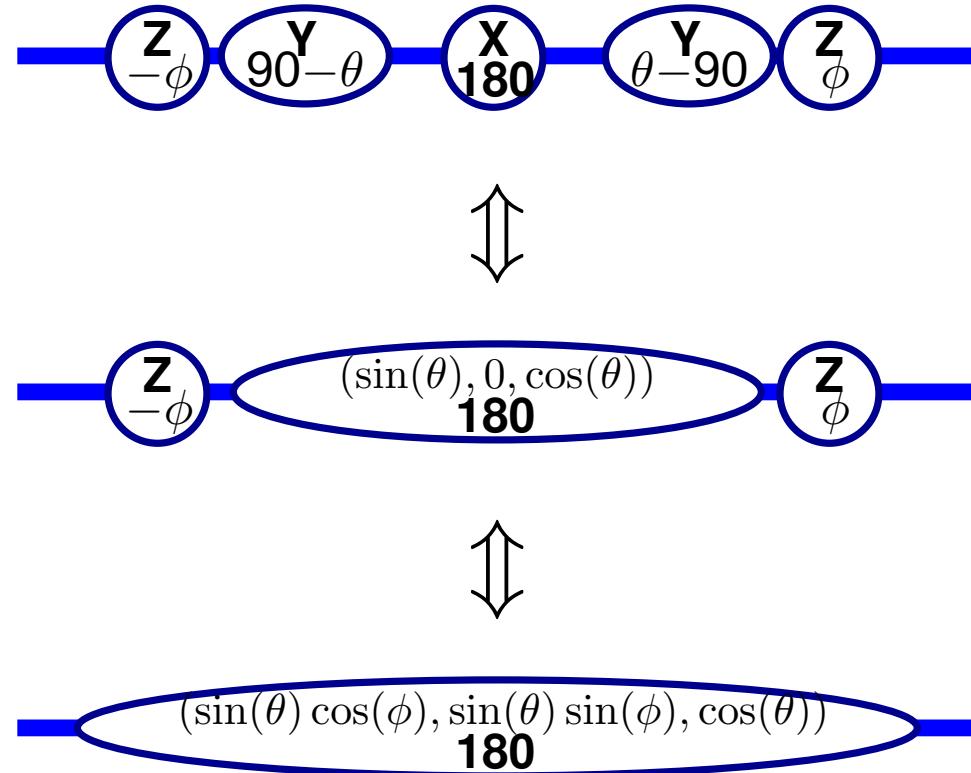
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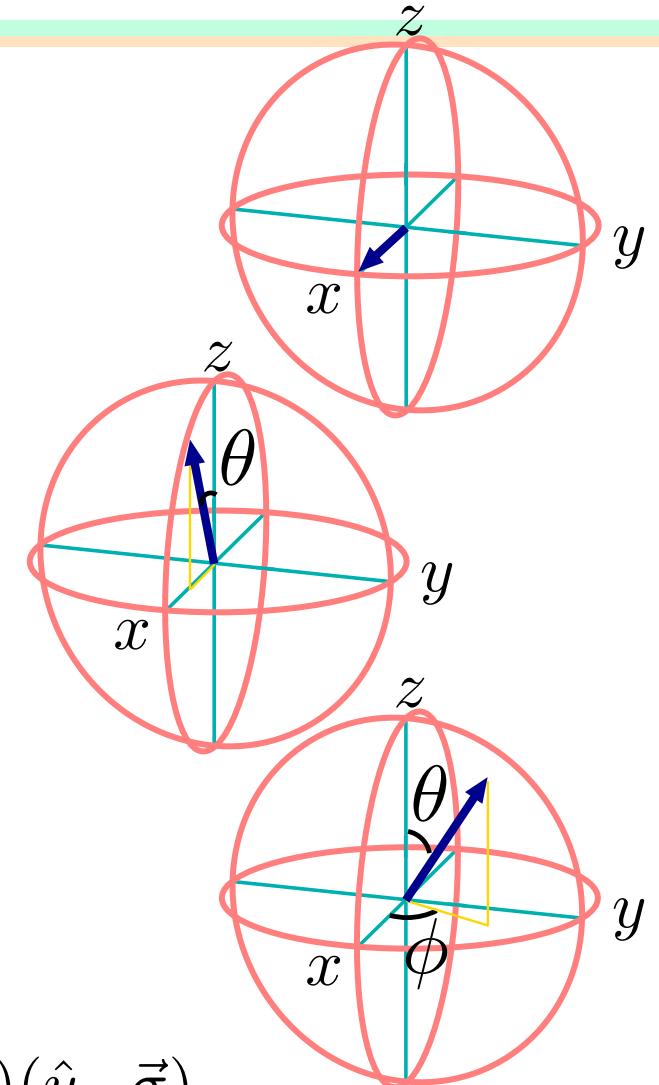
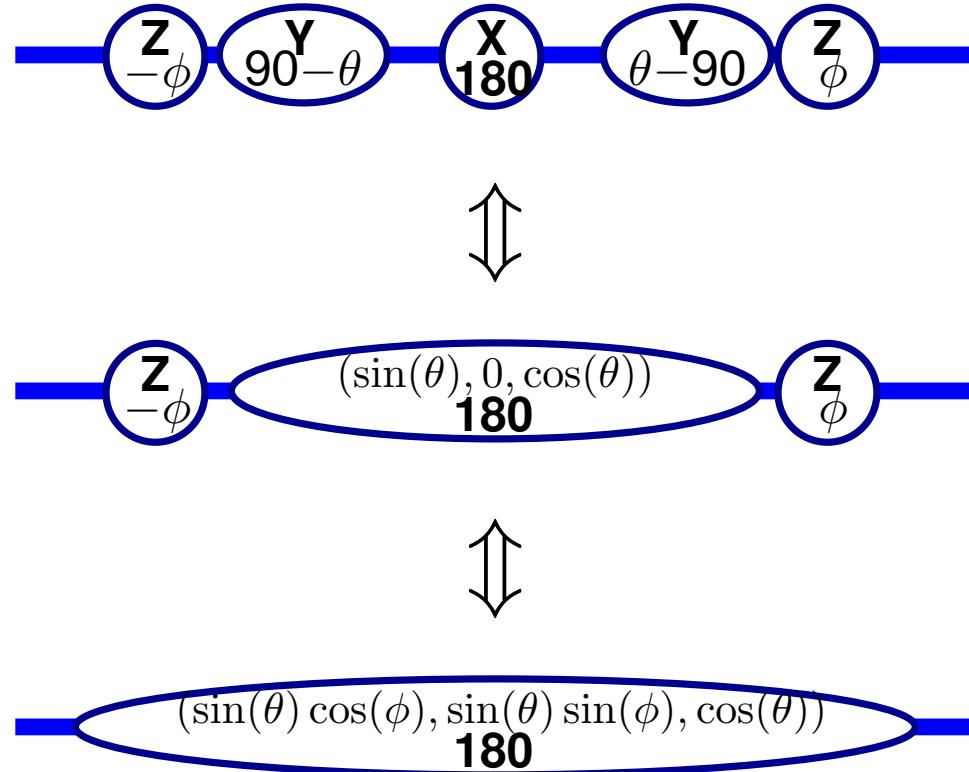
- Rotation with axis  $\hat{u}$  by angle  $\delta$ :

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- Can implement any rotation with 5 major axis rotations.

... three are necessary and sufficient.

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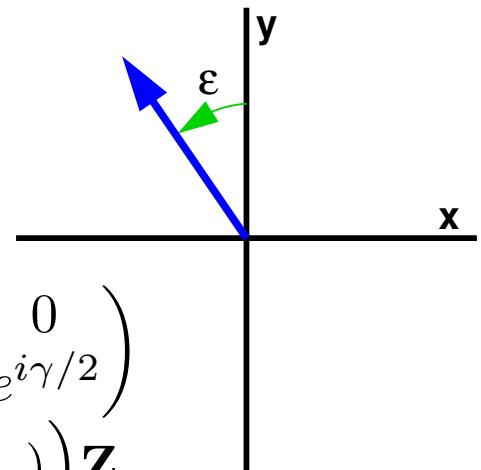
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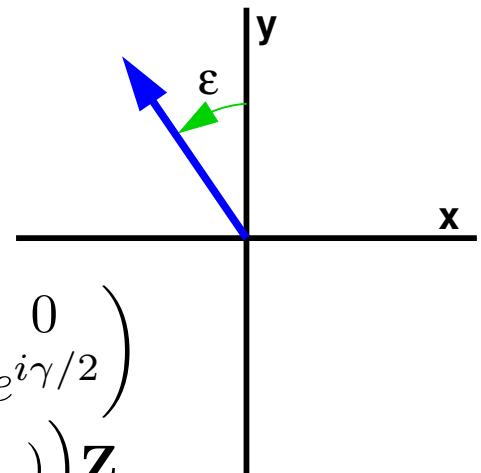
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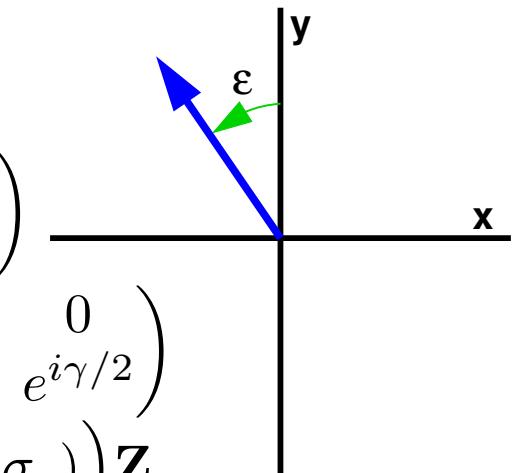
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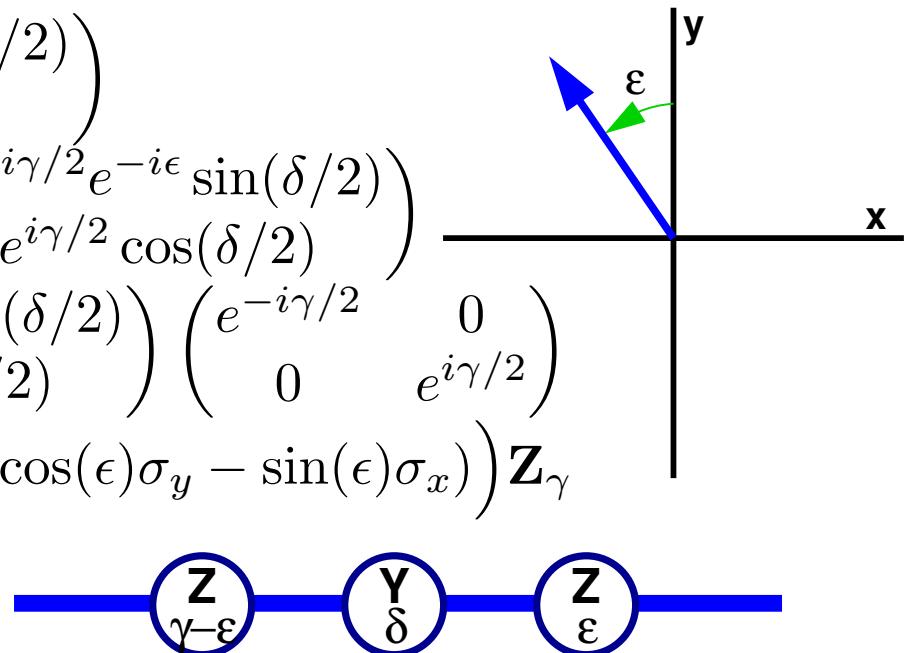
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2.  $U^\dagger U = \mathbb{1}$  implies  $|u_{11}|^2 + |u_{21}|^2 = 1$ : Write  $U = \begin{pmatrix} \cos(\delta/2) & u_{12} \\ e^{i\epsilon} \sin(\delta/2) & u_{22} \end{pmatrix}$

3.  $(\cos(\delta/2), e^{-i\epsilon} \sin(\delta/2)) \begin{pmatrix} u_{12} \\ u_{22} \end{pmatrix} = 0$ .

$$\begin{aligned} U &= \begin{pmatrix} \cos(\delta/2) & -e^{i\gamma} e^{-i\epsilon} \sin(\delta/2) \\ e^{i\epsilon} \sin(\delta/2) & e^{i\gamma} \cos(\delta/2) \end{pmatrix} \\ &= e^{i\gamma/2} \begin{pmatrix} e^{-i\gamma/2} \cos(\delta/2) & -e^{i\gamma/2} e^{-i\epsilon} \sin(\delta/2) \\ e^{-i\gamma/2} e^{i\epsilon} \sin(\delta/2) & e^{i\gamma/2} \cos(\delta/2) \end{pmatrix} \\ &= e^{i\gamma/2} \begin{pmatrix} \cos(\delta/2) & -e^{-i\epsilon} \sin(\delta/2) \\ e^{i\epsilon} \sin(\delta/2) & \cos(\delta/2) \end{pmatrix} \begin{pmatrix} e^{-i\gamma/2} & 0 \\ 0 & e^{i\gamma/2} \end{pmatrix} \\ &= e^{i\gamma/2} \left( \cos(\delta/2) \mathbb{1} - i \sin(\delta/2) (\cos(\epsilon) \sigma_y - \sin(\epsilon) \sigma_x) \right) \mathbf{Z}_\gamma \\ &= e^{i\gamma/2} \mathbf{Z}_\epsilon \mathbf{Y}_\delta \mathbf{Z}_{-\epsilon} \mathbf{Z}_\gamma \\ &= e^{i\gamma/2} \mathbf{Z}_\epsilon \mathbf{Y}_\delta \mathbf{Z}_{\gamma-\epsilon} \end{aligned}$$



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